# NASA TECHNICAL NOTE



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A MODEL FOR SIMULATING RANDOM ATMOSPHERES AS A FUNCTION OF LATITUDE, SEASON, AND TIME

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NATIONAL AERONAUTICS AND SPACE ADMINISTRATION . WASHINGTON, D. C. . SEPTEMBER 1977

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1. Report No. NASA TN		2. Government Accessi	on No.	3.	Recipi	ent's Catalog No.				
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<sup>\*</sup> For sale by the National Technical Information Service, Springfield, Virginia 22161

## A MODEL FOR SIMULATING RANDOM ATMOSPHERES AS A

## FUNCTION OF LATITUDE, SEASON, AND TIME

Janet W. Campbell Langley Research Center

#### SUMMARY

An empirical stochastic computer model has been developed with the capability of generating random thermodynamic profiles of the atmosphere below an altitude of 99 km which are characteristic of any given season, latitude, and time of day. Temperature profiles are generated from multivariate normal distributions, and then density and pressure profiles are calculated from the hydrostatic equation and the equation of state.

Model parameters were estimated by using a set of over 6000 meteorological rocket and high-altitude soundings of the atmosphere. These soundings were divided into 17 latitude-season categories and model parameters were estimated for each category.

Means and standard deviations of model temperatures and vertical temperature gradients are controlled by model input parameters, and hence can be forced to match these properties in the data. Means and standard deviations of model pressures, densities, and their vertical gradients were not controlled directly but do agree well with data. Model-data agreement is particularly good below an altitude of 60 km where the data sample sizes are adequate. Accuracy of the model above 60 km, in most latitude-season categories, is uncertain largely because of the diminished quantity and quality of the data at these heights.

Samples of random atmospheres generated by the model can be used in Monte Carlo studies of the effect of atmospheric variability on spacecraft or aircraft. Other potential uses for the model are in simulating pollutant dispersion patterns, variations in sound propagation, and other phenomena which are dependent on atmospheric properties, and in developing data-reduction software for satellite monitoring systems.

#### INTRODUCTION

#### The Need for a Stochastic Atmosphere Model

In evaluating the performance of aerospace vehicle designs prior to their initial flight, a primary tool has been the wide variety of available trajectory simulation computer programs. These range from simple point-mass programs whose governing equations have closed-form solutions to complex six-degree-of-freedom models requiring numerical solutions of differential or integral equations. Virtually all simulation programs rely on some atmospheric model to provide values of atmospheric temperatures, densities, and pressures as functions of alti-

tude. These atmospheric models, often the U.S. Standard Atmosphere (refs. 1 and 2), provide average estimates of atmospheric properties but do not account for the atmosphere's natural variability, which is appreciable at some altitudes. In the mesosphere (50 to 90 km), for example, atmospheric densities are sometimes twice their predicted U.S. Standard (1962) value. One can observe in available data sets that atmospheric density at the same altitude varies by at least 10 percent within the same season.

In designing an aircraft or spacecraft, an important task is the determination of performance envelopes within which with high probability all flight parameters are expected to lie. In general, a large number of variables contribute to the width of these performance envelopes - atmospheric variability is only one. A common approach to error analyses (that is, to defining the performance envelopes) is to assume that all sources of variation are additive and uncorrelated, and then proceed to estimate their variances separately. this assumption, the total variance is simply the sum of the individual vari-An alternate error analysis approach is to perform Monte Carlo simulations in which the various error sources are treated as random inputs. latter approach, although usually more costly, is often considered to be preferable to the former because it allows natural nonlinearities and interactions to appear in the system. Regardless of which approach is taken, a method is needed to provide an accurate representation of each error source so that its impact on the various performance parameters of interest can be measured. A stochastic atmospheric model is a tool for assessing the impact of atmospheric variability on a performance envelope of the vehicle.

In past design studies on atmospheric entry vehicles, a common method of accounting for atmospheric density variations (refs. 3 and 4) was to calculate trajectories by using both maximum and minimum density profiles as shown in figure 1. Generally, these are profiles in which atmospheric density is two or three standard deviations above or below its mean at all altitudes simulta-This method has two major disadvantages. One is that since density profiles such as these never occur in any real atmosphere, a design parameter based on this method might be overly conservative and, thereby, require unnecessary expense. A second disadvantage, more critical than the first, is that these extreme density profiles do not produce extremes in all entry parameters. For example, it has been shown (ref. 5) that for some vehicles a more severe total heat load is produced when atmospheric density is extremely low as entry begins and suddenly becomes extremely high at lower altitudes. The initial low density causes less deceleration than is normal, and thus the spacecraft encounters an extremely dense atmosphere while traveling at an abnormally high velocity.

To account for the fact that extremes in the various entry parameters are produced by different atmospheric situations, an alternate deterministic approach (ref. 6) has been to determine analytically for each performance parameter the atmospheric profiles which maximize and minimize that parameter, and then design the vehicle to withstand those extremes. As with any deterministic approach, however, this method has the disadvantage that any specific atmospheric profile has a zero probability of occurrence, and thus the design may be overly conservative. Furthermore, the degree of conservatism cannot be ascertained since no

knowledge is provided as to the probability of encountering atmospheres similar to the design atmospheres.

The disadvantages associated with deterministic methods act as justification for the use of statistical methods. A Monte Carlo simulation based on realistic random atmospheres can be used to estimate the statistical distribution of any performance parameter, and design values can be selected for any desired risk or exceedance probability.

The advent of reusable spacecraft with the space shuttle will make it even more important to have good estimates of exceedance probabilities. For example, when a spacecraft was used only once, it was not so critical to distinguish between a failure probability of 0.005 and one of 0.001. With the shuttle having an expected lifetime of 100 missions, however, the difference between single-flight failure probabilities of 0.005 and 0.001 makes the difference between a 40-percent and a 10-percent chance of at least one failure during the lifetime of the shuttle. This condition, therefore, is a further justification for using the best available statistical techniques in design studies to acquire as much confidence as possible in the reliability estimates.

The stochastic atmospheric model described in this report was developed for evaluating the effects of atmospheric variability on the performance parameters of a vehicle (spacecraft or aircraft) along any portion of its trajectory below an altitude of 99 km. The terms "stochastic" and "statistical" will be used interchangeably to describe any model capable of generating random atmospheres. From a sample of random atmospheres, one can construct samples of associated performance parameters such as that illustrated in figure 2. Figure 2 shows histograms (frequency distribution plots) of maximum dynamic pressures which occurred in simulated entries of a space shuttle configuration into random seasonal atmospheres (ref. 7).

## Other Available Stochastic Models

The term "statistical model" sometimes refers to summaries of statistics (usually means and standard deviations) computed from a particular data set (ref. 8). Usually in statistical summaries of this type, no effort is made to model the data. Those who do model the data (ref. 9) generally concentrate on modeling means and standard deviations of the various atmospheric properties as a function of geographic location, but no attempt is made to simulate atmospheres. One of the more thorough efforts of this type is the four-dimensional worldwide model of Spiegler and Fowler (ref. 10) which provides estimates of the mean and standard deviation of atmospheric properties at any location below an altitude of 25 km as a function of longitude and latitude.

Very few stochastic atmosphere models (by the stricter definition) are available, and the few that do exist typically adhere to the belief (sometimes called the "Principle of Parsimony") that the fewer the parameters, the better the model. For the sake of mathematical simplicity, such models compromise their ability to simulate realistic atmospheres. The "Thermodynamic Atmosphere Model" of Engler and Goldschmidt (ref. 11) is an extreme example of this. All atmospheric variability in this model is attributed to a single random variable

which determines the coefficients in an empirical polynomial representing the logarithm of pressure as a function of altitude. Although this model has the advantage of simplicity, its atmospheric profiles, especially that of temperature, approximate realistic profiles only roughly.

An earlier model by the author (ref. 7), although more complex, suffers from the same failing. In this model, systematic variations in stratospheric and mesospheric (30 to 90 km) temperatures were attributed to the variability of ozone concentrations. Ozone variations, generated by an auxiliary model based on four random variables, produced changes in the solar heating rate of ozone, and this process, in turn, produced random temperatures by means of a linear regression scheme. A fundamental shortcoming of this approach is that ozone variations are only one of many sources of variation in the atmosphere. Furthermore, even if all sources of variation were incorporated, the problem of relating their influence to atmospheric temperatures is one which atmospheric scientists have yet to solve.

Another model (ref. 12) with the capability of simulating random atmospheres, although this is not its chief purpose, was developed at the Georgia Institute of Technology under a NASA contract. This model combines the fourdimensional worldwide model of reference 10 with other models of higher regions extending to orbital altitudes. Its primary aim is to provide estimates of means and standard deviations for atmospheric properties as functions of longitude and latitude (globally) for each month of the year. Wide bands of uncertainty exist about the estimates because of the limited amount of data used in their construction. In fact, if all available atmospheric data were used as a data base for a model of such fine spacial and temporal resolution, error bands would still be appreciable over most regions of the glove. To generate random atmospheres, this model uses a set of approximations (ref. 13), which relate means and variances of atmospheric properties to the correlations between properties, based on the assumption that percentage departures from the mean are small. Reference 12 does not comment as to its accuracy in simulating random atmospheres.

## The ERA Model

The model reported here will be called the ERA (empirical random atmosphere) model. The central goal throughout the modeling process was to imitate a data set consisting of over 6000 meteorological rocket and high-altitude sounding measurements. As will be demonstrated, the ERA model is capable of generating samples of random atmospheres for different seasons and latitude zones which are statistically similar to samples of measured atmospheres in those seasons and latitude zones. The model attempts to match means and standard deviations not only of the thermodynamic properties themselves, but also of their vertical gradients. Because a unified approach was taken in estimating model parameters, and because of the substantial size of the data base of the model, the ERA model is, in the author's judgment, the best available model for simulating realistic random atmospheres.

## Other Applications

Although the ERA model was developed as a tool for evaluating space vehicle performances when exposed to random atmospheres, potential applications of the model are certainly not limited to this area. Other potential uses include studies of the effect of atmospheric variability on sound propagation or pollutant dispersion patterns. The ERA model can also be used to simulate random atmospheres for use in developing data-reduction software for satellite monitoring systems. Any phenomenon which is affected by atmospheric temperatures, densities, or pressures would also be affected by the variability of these properties and hence can be studied by this model. In addition, the large number of summary plots detailing statistical properties of the atmosphere at different latitudes and seasons may be of interest solely for their information content, apart from the model.

#### SYMBOLS

a <sub>0</sub> ,a <sub>1</sub> ,a <sub>2</sub>	coefficients of linear regression of sea-level pressure on sea-level temperature
В	lower triangular matrix satisfying $BB^{t} = C$
b <sub>ij</sub>	element in ith row and jth column of B
С	correlation matrix for temperature vector T
c <sub>ij</sub>	element in ith row and jth column of C matrix; coefficient of linear correlation between $\textbf{T}_{\dot{1}}$ and $\textbf{T}_{\dot{j}}$
c <sub>ij</sub> *	adjusted element of C matrix required to make C positive definite
D	column vector of atmospheric densities at altitude intervals of 3 km between sea level and 99 km, $kg/m^3$
Di	element of D vector at altitude $z_i$ , $kg/m^3$
E( )	mean or expected value operator
G	universal gas constant, $8.314 \times 10^3$ J/K
g	acceleration due to gravity, m/sec <sup>2</sup>
g <sub>0</sub>	acceleration due to gravity at sea level, m/sec <sup>2</sup>
<b>ē</b> i	"effective" acceleration due to gravity between $z_{i-1}$ and $z_i$ , m/sec <sup>2</sup>
M	mean molecular weight of air, 28.964 kg
n	total number of soundings in data sample for a latitude-season category
n <sub>i</sub>	total number of observations of $T_i$ in data sample

```
total number of soundings in data sample in which both T_i and T_i
n_{i,j}
              are measured
Ρ
            column vector of atmospheric pressures at altitude intervals of 3 km
              between sea level and 99 km, N/m<sup>2</sup>
            element of P vector at altitude z<sub>i</sub>, N/m<sup>2</sup>
Ρi
            value of P<sub>i</sub> at time of kth sounding, N/m<sup>2</sup>
P_{ik}
\bar{P}_1
           mean sea-level pressure, N/m<sup>2</sup>
            standardized pressure at altitude zi
Рi
R_{O}
           radius of Earth, m
           coefficient of linear correlation between sea-level temperature and
ттр
              sea-level pressure
           coefficient of linear correlation between sea-level temperature and
r_{TR}
              zenith angle of Sun
S( )
           standard deviation operator
s_i
           standard deviation of Ti, K
T
           column vector of atmospheric temperatures at altitude intervals of
             3 km between sea level and 99 km, K
T_i
           element of T vector at altitude z<sub>i</sub>, K
Tik
           value of T<sub>i</sub> at time of kth sounding, K
Τį
           sample mean of all observations of Ti, K
ti
           standardized temperature at altitude zi
           column vector of mutually independent, standardized normal (Gaussian)
             random variables
           element of x vector
x_i
Z
           altitude, km
z_i
           altitude level corresponding to 3(i - 1) km
          coefficients of linear regression of standardized sea-level
\alpha_0, \alpha_1, \alpha_2
             temperature on zenith angle of Sun
ß
           zenith angle of Sun, deg
B
          average of zenith angles associated with soundings in data sample, deg
6
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\Delta D_i = D_i - D_{i-1}, \, kg/m^3
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$$\Delta P_i = P_i - P_{i-1}, N/m^2$$

$$\Delta T_i = T_i - T_{i-1}, K$$

$$\Delta z = z_i - z_{i-1}, 3 \text{ km}$$

$$\delta_{ik}$$
 binary function indicating whether  $T_{ik}$  is measured ( $\delta_{ik}$  = 1) or missing ( $\delta_{ik}$  = 0)

$$\delta_{ik}^{*}$$
 binary function indicating whether  $P_{ik}$  is measured ( $\delta_{ik}^{*}$  = 1) or missing ( $\delta_{ik}^{*}$  = 0)

$$\sigma_i$$
 element of  $\sigma$  vector corresponding to standard deviation of temperature at altitude  $z_i$ ,  $K$ 

$$\sigma_{\beta}$$
 standard deviation of Sun zenith angles in data sample, deg

$$\tau_i$$
 element of  $\tau$  vector corresponding to mean temperature at altitude  $z_i$ ,  $K$ 

## Superscript:

t transpose of matrix

#### Subscripts:

i altitude level 
$$3(i-1)$$
 km  $(i=1, \ldots, 34)$ 

j altitude level 
$$3(j-1)$$
 km  $(j=1, \ldots, 34)$ 

k sounding number in a sample of n soundings 
$$(k = 1, ..., n)$$

#### Abbreviations:

ERA empirical random atmosphere

MRN Meteorological Rocket Network

NCC National Climatic Center, NOAA, Asheville, NC

#### FORMULATION OF MODEL

## Objective

The objective of the ERA model is to provide random atmospheres extending to approximately 100 km which are typical of any given season, latitude, and time of day. Each atmosphere consists of three thermodynamic profiles, where the term "profile" refers to a column vector of dimension 34 whose elements correspond to altitudes 0, 3, . . ., 99 km. The three thermodynamic profiles are

$$T = \begin{bmatrix} T_1 \\ T_2 \\ \cdot \\ \cdot \\ \cdot \\ T_3 4 \end{bmatrix} \qquad D = \begin{bmatrix} D_1 \\ D_2 \\ \cdot \\ \cdot \\ \cdot \\ D_3 4 \end{bmatrix} \qquad P = \begin{bmatrix} P_1 \\ P_2 \\ \cdot \\ \cdot \\ \cdot \\ P_3 4 \end{bmatrix}$$
 (1)

where  $T_1$ ,  $D_1$ , and  $P_1$  are sea-level temperature, density, and pressure, respectively;  $T_2$ ,  $D_2$ , and  $P_2$  are these properties at an altitude of 3 km, and so forth.

The criteria by which model-generated atmospheres are judged to be "typical" are based on certain statistical properties of large samples of model-generated atmospheres. Specifically, the following statistical properties of any model-generated sample should match, within sampling errors, the same properties of atmospheric data samples:

- (1) Mean and standard deviation of  $T_i$  (i = 1, . . . , 34)
- (2) Mean and standard deviation of  $D_i$  (i = 1, . . . , 34)
- (3) Mean and standard deviation of  $P_i$  (i = 1, . . . , 34)
- (4) Means and standard deviations of vertical gradients dT/dz, dD/dz, and dP/dz

The three vectors T, D, and P representing any one atmosphere generated by the model are mutually consistent in that they are related by the equation of state and the hydrostatic equation. The equation of state (ideal gas law) determines one thermodynamic property from the other two by the relationship

$$D_{i} = \frac{\overline{M}P_{i}}{GT_{i}}$$
 (i = 1, ..., 34)

where  $\overline{M}$  is the mean molecular weight of air (28.964 kg) and G is the universal gas constant (8.314 x 10<sup>3</sup> J/K).

The hydrostatic equation

$$\left(\frac{dP}{dz}\right)_{z=z_{i}} = -g(z_{i})D_{i}$$
(3)

attributes vertical pressure differentials between two altitudes to the weight of the air between those levels. Although it is known that the equation of state and the hydrostatic equation are approximations (for example,  $\bar{\mathbf{M}}$  varies at high altitudes and atmospheric dynamics disrupt hydrostatic equilibrium), they are widely used in atmospheric models. (See refs. 1 and 2.) Where the data contained two or three simultaneously measured profiles, it was found that these equations were satisfied quite adequately.

The effect of using equations (2) and (3) is a reduction of the degrees of freedom in the model. Given one profile and a boundary condition for another, the two remaining profiles are uniquely determined. The ERA model starts with a random temperature profile and a random sea-level pressure, which are generated by a stochastic model, and uses these values to calculate the remaining atmospheric properties  $(P_2, \ldots, P_{34})$  and  $(D_1, \ldots, D_{34})$  by equations (2) and (3). Thus, the ERA model is essentially a stochastic temperature model with deterministically derived pressures and densities.

Experience has shown that temperature is the best choice for the "given" profile used in solving equations (2) and (3). Otherwise, derived temperature profiles with the proper shape are difficult to produce. Pressures or densities which deviate slightly from their "true" shapes can produce temperature profiles of a highly unnatural form. For example, suppose one wished to use pressure as the "given" profile by modeling  $\log P$  as a polynomial function in z with random coefficients as in reference 11. A plot of  $\log P$  against z appears nearly linear. However, it is possible to show that the order of this polynomial must be five or greater in order that dT/dz = 0 at three altitudes (tropopause, stratopause, and mesopause). Thus, one must include higher order terms, even though small, since these are crucial for modeling the T profile adequately.

#### Temperature Model

Atmospheric temperature at altitude  $z_i$  (i = 1, . . ., 34) is given by the equation

$$T_{i} = \tau_{i} + t_{i}\sigma_{i} \tag{4}$$

where  $\tau_i$  and  $\sigma_i$  are the mean and standard deviation, respectively, of temperature at altitude  $z_i$ , and  $t_i$  is a standardized (with mean of 0 and standard deviation of 1) random variable from a probability distribution which will be specified. The parameter vectors  $\tau$  and  $\sigma$ 

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \cdot \\ \cdot \\ \cdot \\ \tau_{34} \end{bmatrix} \qquad \sigma = \begin{bmatrix} \sigma_1 \\ \sigma_2 \\ \cdot \\ \cdot \\ \cdot \\ \sigma_{34} \end{bmatrix} \tag{5}$$

are estimated from data for different seasons and latitude zones.

The  $t_i$  values are assumed to have a variance-covariance matrix C whose elements  $c_{ij}$  are defined so that  $c_{ij} \equiv c_{ji} \equiv \text{Covariance}$  of  $t_i$  and  $t_j$ . The  $t_i$  values are standardized temperatures since they represent departures from the mean in units of  $\sigma_i$ ; that is,

$$t_{i} = \frac{T_{i} - \tau_{i}}{\sigma_{i}} \tag{6}$$

Thus, the covariance of  $t_i$  and  $t_j$ ,

$$e_{ij} = E(t_i t_j) = \frac{E\left[(T_i - \tau_i)(T_j - \tau_j)\right]}{\sigma_i \sigma_j}$$
(7)

is, by definition, the coefficient of linear correlation between  $T_i$  and  $T_j$ . Thus, C is also the correlation matrix for the T vector.

The method of generating a vector

$$t = \begin{bmatrix} t_1 \\ t_2 \\ \vdots \\ \vdots \\ t_{34} \end{bmatrix}$$

$$(8)$$

of standardized random numbers with correlation matrix C is based on the following theorem (ref. 14):

Theorem. Let x be a vector of independent standardized random numbers and let C be a correlation matrix (i.e., C is real, symmetric, positive semidefinite, and its elements  $c_{ij}$  satisfy  $c_{ii}$  = 1 and  $|c_{ij}| \le 1$ ). Let B be a real matrix satisfying

$$C = BB^{t}$$
 (9)

where Bt is the transpose of B. Then the vector

$$t = Bx ag{10}$$

is a vector of standardized random numbers whose covariance matrix is C.

Proof of this theorem, omitted here, is straightforward by using the definitions of statistical moments.

The existence of a real matrix B as defined in equation (9) results from the fact that C is positive semidefinite, but B is not unique. If C is positive definite (that is, there are no linear dependencies among the  $t_i$  values), then a convenient choice for B is a unique lower triangular matrix obtained by using Cholesky's decomposition method (discussed in ref. 15). Elements of B are obtained recursively as follows:

$$b_{11} = (c_{11})^{1/2} (11)$$

$$b_{i1} = \frac{c_{i1}}{b_{11}} \tag{12}$$

$$b_{jj} = \left(c_{jj} - \sum_{k=1}^{j-1} b_{jk}^{2}\right)^{1/2}$$
 (j > 1)

$$b_{ij} = \begin{cases} 0 & \text{(i < j)} \\ c_{ij} - \sum_{k=1}^{j-1} b_{ik} b_{jk} \\ \hline b_{jj} & \text{(i > j > 1)} \end{cases}$$

The B matrices for different seasons and latitude bands were calculated from estimates of the correlations  $c_{i\,j}$ . Details of the process of estimating model parameters will be given in the next section of this paper.

So far, the development of the temperature model has been general for any choice of a statistical distribution for T. In the ERA model, T is assumed to be a multivariate normal (Gaussian) random variable. This choice was not made on the basis of observed temperature distributions in the data, although

the latter do appear qualitatively to have Gaussian shapes, but the choice was one of mathematical expediency. The additive property of normal random variables, which states that any linear combination of independent normal random variables is itself normal, permits the convenience of using a normally distributed x vector in equation (10). For an arbitrary T distribution not possessing this additive property, the distributions of the x variates must be estimated by using characteristic functions (similar to Fourier transforms) of the T distribution functions. (See ref. 14.) The mathematical complexity involved in such an approach did not appear to be warranted for the purposes for which the ERA model is intended; that is, it is believed that parameter distributions resulting from Monte Carlo simulations using the ERA model are insensitive to the choice of the T distribution provided that its first two moments are estimated with sufficient accuracy.

The triangular form of B gives the following system of equations:

$$t_{1} = b_{11}x_{1}$$

$$t_{2} = b_{21}x_{1} + b_{22}x_{2}$$

$$t_{3} = b_{31}x_{1} + b_{32}x_{2} + b_{33}x_{3}$$

$$\vdots$$

$$t_{34} = b_{34}, 1x_{1} + b_{34}, 2x_{2} + \cdots + b_{34}, 34x_{34}$$
(15)

where the  $x_i$  values are a set of mutually independent, standardized normal random numbers provided by a random number generator. In the first equation,  $b_{11} = 1$  since  $c_{11} = 1$ . Thus, the sea-level standardized temperature  $t_1$  is the standardized normal random number  $x_1$  which is selected first and, in a sequential sense, is independent of all other variables at the time it is generated. Subsequently,  $t_2$  is correlated to  $t_1$ ;  $t_3$  is correlated to  $t_1$  and  $t_2$ ; and so forth. If no information regarding calendar date and time of day is provided, then the temperature vector  $t_1$  is constructed in this manner.

However, if the date and time are specified, temperatures are adjusted to reflect their diurnal variation. The zenith angle of the Sun  $\beta$  is calculated (from latitude, longitude, date, and time) and  $t_1$  is correlated to  $\beta$  by an adjustment of  $x_1$ . The  $\beta$ -dependent  $x_1$  is given by

$$x_1(\beta) = \alpha_0 + \alpha_1 \beta + \alpha_2 x_1$$
 (16)

where  $x_1$  on the right-hand side is the former independent random number. The regression coefficients  $\alpha_0$ ,  $\alpha_1$ , and  $\alpha_2$  are constants which have been estimated for different seasons and latitude regions. The adjusted  $x_1(\beta)$  is then used in the system of equations (15) to calculate the t vector.

## Calculating Atmospheric Pressures and Densities

Once the temperature profile is generated, a sea-level pressure is obtained by the model

$$P_1 = a_0 + a_1 T_1 + a_2 p_1 \tag{17}$$

where the regression coefficients  $a_0$ ,  $a_1$ , and  $a_2$  are estimated from data for each season and latitude region, and  $p_1$  is a standardized normal random number. Thus, sea-level pressure is assumed to be normally distributed and correlated linearly to sea-level temperature.

The sea-level pressure and the temperature profile, together with some assumption about how temperature varies between  $z_i$  and  $z_{i+1}$ , are sufficient to define the remaining atmospheric properties by using the equation of state (eq. (2)), and the hydrostatic equation (eq. (3)). The following solution is that used in U.S. Standard Atmosphere (refs. 1 and 2).

The density  $D_i$  in equation (3) is replaced with its equivalent from equation (2) to give the integral equation

$$P_i = P_1 \exp \left[ -\frac{\bar{M}}{G} \int_0^{z_i} \frac{g(z) dz}{T(z)} \right]$$
 (i = 2, ..., 34)

The acceleration due to gravity at altitude z is given by

$$g(z) = g_0 \left(\frac{R_0}{R_0 + z}\right)^2 \tag{19}$$

where  $g_0$ , the value of g at sea level and latitude  $\phi$ , is

$$g_0 = 9.780 \ 356(1 + 0.005 \ 288 \ 5 \ \sin^2 \phi)$$
 (20)

in  $m/\sec^2$  and  $R_0$ , the Earth's radius at latitude  $\phi$ , is

$$R_0 = 6 356 798(0.993 307 0 + 0.006 693 0 sin |\phi|)^{-1/2}$$
 (21)

in meters. By assuming that temperature varies linearly with altitude between the discrete altitudes  $z_i$  (i = 1, . . ., 34), equation (18) can be integrated to give the elements of the pressure profile as

$$P_{i} = P_{i-1} \left( \frac{T_{i}}{T_{i-1}} \right)^{-\overline{g}_{i} \overline{M} \Delta z / G \Delta T_{i}}$$

$$(\Delta T_{i} \neq 0)$$
(22a)

$$P_{i} = P_{i-1} \exp \left( \frac{-\bar{g}_{i}\bar{M} \Delta z}{G \Delta T_{i}} \right) \qquad (\Delta T_{i} = 0) \qquad (22b)$$

where  $i=2,\ldots,34$ ,  $\Delta z=3$  km,  $\Delta T_i=T_i-T_{i-1}$ , and  $\bar{g}_i$  is the "effective" gravitational acceleration between  $z_{i-1}$  and  $z_i$  given by

$$\bar{g}_{i} = \frac{g_{0}R_{0}^{2}}{(R_{0} + z_{i})(R_{0} + z_{i-1})}$$
 (23)

Once T and P are determined, the equation of state gives the density profile as

$$D_{i} = \frac{\overline{M}P_{i}}{GT_{i}}$$
 (i = 1, ..., 34)

A program of the model has been written and is available through the Computer Software Management and Information Center (COSMIC) at the University of Georgia under the name ERA (number LAR-12228). The program user can specify latitude, longitude, calendar date, time of day, and the number of random atmospheres required. The program will then simulate that number of atmospheres and store them on an output tape for later use. If the user specifies a requirement of 0 atmospheres, the program sets T = T and  $P_1$  equal to its mean and solves the equation of state and the hydrostatic equation with these mean conditions and then stores the resultant profiles on the output tape.

## ESTIMATION OF PARAMETERS

The model parameters, as defined in the preceding section, are

- (1)  $\tau$  and  $\sigma$ , the mean and standard deviation (vectors) of the temperature profile T
- (2) B, the lower triangular matrix defined so that BB<sup>t</sup> = C where C is the correlation matrix of the T vector
- (3)  $\alpha_0$ ,  $\alpha_1$ , and  $\alpha_2$ , coefficients of the linear regression of standardized sea-level temperature  $t_1$  on the zenith angle of the Sun  $\beta$
- (4)  $a_0$ ,  $a_1$ , and  $a_2$ , coefficients of the linear regression of sea-level pressure  $P_1$  on sea-level temperature  $T_1$ .

In order to estimate these parameters for different locations and seasons, a set of approximately 6000 rocket and high-altitude soundings of the atmosphere was utilized. The data were divided into 17 latitude-season categories and a complete set of parameters, as listed above, was estimated for each category. These parameter sets are stored on an auxiliary parameter tape which can be linked to any computer program of the model.

#### Data Base \*

Measured profiles of the atmosphere comprising the model's data base were acquired from two sources. Approximately 5600 of these soundings were on 12 magnetic tapes furnished by the National Climatic Center (NCC), Environmental Data Service, of the National Oceanic and Atmospheric Administration. The NCC tapes were compiled from Meteorological Rocket Network (MRN) soundings made at numerous sites around the world between 1969 and 1971 (inclusive). Details of the MRN program, including sounding techniques and accuracy, may be found in reference 16. In most cases, these soundings do not extend above 60 km. To extend the data base to higher altitudes, a supplementary tape of 442 highaltitude soundings was acquired from Dale L. Johnson of NASA Marshall Space Flight Center.

The soundings were divided into categories according to the latitude zone and season in which each sounding was made. The five latitude zones

Zone	Latitudes, <sup>O</sup> N or <sup>O</sup> S
150 band	0 to 22.5
30° band	22.51 to 37.5
45° band	37.51 to 52.5
60° band	52.51 to 67.5
75° band	67.51 to 90.0

are those used in the 1966 U.S. Standard Atmosphere Supplements (ref. 2). Soundings which fell into one of the nonequatorial latitude bands were also classified by their season. The four season categories are:

Season	Northern hemisphere	Southern hemisphere
Spring	March to May	September to November
Summer	June to August	December to February
Autumn	September to November	March to May
Winter	December to February	June to August

Soundings in the 15° latitude band were not classified by season since seasonal differences are considered to be negligible at these latitudes. Table I lists the resultant 17 latitude-season categories and the number of soundings which belong to each. Since the soundings seldom cover the entire altitude range (0 to 99 km), the number of observations at each altitude is less than the number

of profiles shown in table I. Tables II, III, and IV show the actual number of temperature, pressure, and density observations, respectively, at each altitude level after a filter was applied to eliminate unreasonable points.

The drastic reduction in available data above 60 km is readily apparent. Where data are sparse, parameter estimates are very uncertain. Bands of uncertainty in the form of 90-percent confidence intervals will be shown in later figures. Where data are completely missing, "fictitious" parameter estimates are made for the sake of completeness. A later section of this paper discusses that procedure.

## Notation and Terminology

It is customary for statisticians to differentiate notationally between true population parameters, which generally remain unknown, and estimates of these parameters which are based on data. For example, if the true mean temperature at altitude  $z_i$  is denoted  $\tau_i$ , an estimate of  $\tau_i$  based on a data sample might be denoted  $\hat{\tau}_i$ . The parameter  $\tau_i$  is a fixed "State of Nature," whereas the estimate  $\hat{\tau}_i$  is itself a random variable which changes as the data changes. In the present paper, however, no such distinction is made explicitly. Estimates of the model parameters listed share the same notation as the parameters themselves. It is believed that readers can distinguish, when necessary, between the two meanings by the context in which the symbol is used.

The fact that the data are incomplete in that very few soundings cover the entire altitude range (0 to 99 km) complicates the parameter estimation task and the notation involved in defining the estimators which were used. The system of notation for treating incomplete data which will be used is described as follows.

Let n be the number of soundings in the data base for the latitude-season category in question (from table I), and let  $T_{ik}$  (i = 1, . . ., 34; k = 1, . . ., n) be the value of  $T_i$  at the time of the kth sounding. Define the variable  $\delta_{ik}$  as

$$\delta_{ik} = \begin{cases} 1 & (\text{if } T_{ik} \text{ is present}) \\ 0 & (\text{if } T_{ik} \text{ is missing}) \end{cases}$$
 (25)

Thus,  $n_i$ , the number of temperature observations at altitude  $z_i$  (from table II), is given by

$$n_{i} = \sum_{k=1}^{n} \delta_{ik} \tag{26}$$

and  $n_{i,j}$ , the number of soundings in which both  $T_i$  and  $T_j$  are measured, is

$$n_{ij} = \sum_{k=1}^{n} \delta_{ik} \delta_{jk}$$
 (27)

Estimating  $\tau$  and  $\sigma$ 

The most common estimators for the mean and standard deviation of  $\,T_{\dot{1}}\,\,$  are the sample mean

$$\bar{T}_{i} = \frac{\sum_{k=1}^{n} \delta_{ik} T_{ik}}{n_{i}}$$
(28)

and the sample standard deviation

$$s_{i} = \begin{bmatrix} \frac{n}{\sum_{k=1}^{n} \delta_{ik} (T_{ik} - \bar{T}_{i})^{2}} \\ \frac{n_{i} - 1}{n_{i} - 1} \end{bmatrix}^{1/2}$$
 (29)

If the model parameters  $\tau_i$  and  $\sigma_i$  are set equal to  $\bar{T}_i$  and  $s_i$ , respectively, means and standard deviations of model temperatures can be forced to match those in the data exactly. The ERA model, however, does not use  $\bar{T}_i$  and  $s_i$  as estimators for the mean and standard deviation of  $T_i$ . Instead, estimators were selected to improve the fit of Gaussian distributions to the observed temperature distributions.

The parameters  $\tau_i$  and  $\sigma_i$  were obtained as follows: Temperatures in the data corresponding to cumulative frequencies of 0.26, 0.5, and 0.84 were set equal to  $\tau_i$  -  $\sigma_i$ ,  $\tau_i$ , and  $\tau_i$  +  $\sigma_i$ , respectively, and these three equations were solved for the best (least-squares) values of  $\tau_i$  and  $\sigma_i$ . The similarity between model (Gaussian) and data temperature distributions is reflected in the fact that  $\tau_i$  and  $\sigma_i$  agreed closely with  $\bar{T}_i$  and  $s_i$  at most altitudes.

An advantage of the method used for estimating  $\tau_i$  and  $\sigma_i$  over the usual estimators  $\bar{T}_i$  and  $s_i$  is that the former method is much less sensitive to erratic behavior in the tails of the data distribution. For example, if the data samples contain outliers of questionable validity, these tend to inflate  $s_i$  whereas they have little effect, in general, on the estimate  $\sigma_i$  based on cumulative frequencies. This is an important consideration in estimation problems such as this where individual point-by-point decisions on data validity are precluded by the large volume of data involved.

### Estimating B

The coefficient of correlation between  $T_i$  and  $T_j$  was estimated as

$$c_{ij} = \frac{\sum_{k=1}^{n} \delta_{ik} \delta_{jk} (T_{ik} - \tau_{i}) (T_{jk} - \tau_{j})}{\left[\sum_{k=1}^{n} \delta_{ik} \delta_{jk} (T_{ik} - \tau_{i})^{2} \sum_{k=1}^{n} \delta_{ik} \delta_{jk} (T_{jk} - \tau_{j})^{2}\right]^{1/2}}$$
(30)

Note that summations in the numerator and denominator include only data where both  $T_i$  and  $T_j$  are measured; that is, the  $\delta_{ik}\delta_{jk}$  product appears in all three sums. This estimator is used because it insures that  $\left|c_{i,j}\right| \leq 1$ . To see this, note that  $c_{i,j}$  takes the form of the cosine of the angle between two n-dimensional vectors whose kth components are  $\delta_{ik}\delta_{jk}(T_{ik}-\tau_i)$  and  $\delta_{ik}\delta_{jk}(T_{jk}-\tau_j)$ .

In all 17 latitude-season categories the C matrices, as defined by equation (30), failed to be positive definite, a requirement needed to apply the Cholesky decomposition, equations (11) to (14), to obtain B. It is possible to show that had the data set been complete ( $\delta_{ik}$  = 1 for all i and k) C would have been positive definite. In this case C could be expressed as the product UU<sup>t</sup> where U is the 34 × n matrix of rank 34 whose elements are

$$u_{ik} = \frac{T_{ik} - \tau_i}{\left[n \sum_{l=1}^{n} (T_{il} - \tau_i)^2\right]^{1/2}}$$
(31)

for  $i=1,\ldots,34$ ;  $k=1,\ldots,n$ . A matrix of full rank is positive definite if, and only if, it can be expressed as  $UU^t$  for some matrix U. (See ref. 17.) This same matrix U does not work for the case of incomplete data because the sums of squares in the denominator of equation (30) are dependent on both i and j indices.

In general, C matrices defined by equation (30) may still be positive definite. In fact, the first 20 rows and columns of the C matrices involved in the ERA model were positive definite. These values correspond to altitudes below 60 km where samples were much more complete. Above 60 km, missing data and possibly other anomalies in the data began to impact the estimates of correlations to such an extent that C no longer was positive definite.

In each of the 17 data sets, the nonpositive nature of C was encountered in calculating the B matrix, recursively, when the right-hand side of equation (13) became the square root of a negative number. In each case j was greater than 20 so that at least the first 20 rows and columns of B had been successfully defined.

A means of overcoming this problem was sought which would keep the successfully defined portion of B intact and modify only the row and column of C where the difficulty was encountered. In addition, it was decided to allow all elements of that row and column to be modified except the diagonal and first off-diagonal elements. That is, if this is the mth row (column),  $T_{m-1}$  and  $T_{m+1}$  would retain their estimated correlations with  $T_m$  but the correlation of the other  $T_{\dot{1}}$  values with  $T_m$  could be changed. Since the variance of the vertical temperature gradient at  $z_{\dot{1}}$  is dependent on  $c_{m,m-1}$  and  $c_{m,m+1}$ , this condition was imposed to maintain an accurate modeling of the temperature gradient.

The simplest regression model of  $t_m$  on  $t_{m-1}$  was selected; namely,

$$t_{m} = \lambda_{m} t_{m-1} + \varepsilon_{m} \sqrt{1 - \lambda_{m}^{2}}$$
 (32)

where  $\lambda_m$  is a constant and  $\epsilon_m$  is a standardized random variable which is independent of  $t_i$  (i < m). It is straightforward to show that  $\lambda_m = c_{m,m-1}$  retains the desired correlation between  $T_m$  and  $T_{m-1}$ . The remaining correlations are

$$E(t_m t_i) = \lambda_m \ E(t_{m-1} t_i) = c_{m,m-1} c_{m-1,i}$$
(33)

for  $i=1,\ldots,m-2$ . Thus, when a row m was encountered so that  $b_{mm}$  was imaginary, the correlations  $c_{mi}$  and  $c_{im}$  (i < m-1), were replaced by

$$c_{mi}^* = c_{im}^* = c_{m,m-1}c_{m-1,i}$$
 (34)

It is possible to show, by using equations (11) to (14), that the problem of a nonpositive-definite C matrix is thereby solved. The adjusted mth row of the B matrix becomes

$$b_{mi}^* = c_{m,m-1}b_{m-1,i}$$
 (1 \leq i < m) (35)

and

$$b_{mm}^* = \left[c_{m,m} - \sum_{i=1}^{m-1} (b_{mi}^*)^2\right]^{1/2} = (1 - c_{m,m-1}^2)^{1/2}$$
(36)

is always real.

The physical significance of the model given by equation (32) is that the conditional distribution of  $T_m$  when given  $T_{m-1}$  is independent of the temperatures at levels below  $z_{m-1}.$  In other words, if one wishes to estimate  $T_m$  when given other temperatures lower in the atmospheric profile, knowledge of  $T_{m-1}$  is sufficient and the additional knowledge of lower temperatures is of no value. No attempt was made to justify the use of equation (32) on the basis of this physical significance. The model was chosen because it preserves the modeling of  $\Delta T_m/\Delta z$  and because it guarantees a real B matrix. It is interesting to note that this adjusted C matrix is optimal in that it corresponds, for a particular choice of weights, to an optimal solution derived by Carswell (ref. 14) for correcting a nonpositive-definite correlation matrix.

In summary, the B matrix elements were estimated by applying equations (11) to (14) to the correlation matrix C whose elements are defined by equation (30). If the correlations in some row M of the C matrix were such that the element  $b_{mm}$  defined by equation (13) was not real, then the mth row and column of the C matrix were modified by using equation (34). This procedure corrected the problem in a physically meaningful manner and preserved the modeling of temperature gradients found in the data.

Estimating 
$$\alpha_0$$
,  $\alpha_1$ , and  $\alpha_2$ 

A linear regression of the standardized sea-level temperature on  $\beta$ , the zenith angle of the Sun, was estimated as follows: Let  $r_{T\beta}$  be the coefficient of linear correlation between  $T_1$  and  $\beta$  defined by

$$r_{T\beta} = \frac{\sum_{k=1}^{n} \delta_{1k} (T_{1k} - \tau_1) (\beta_k - \bar{\beta})}{\left[\sum_{k=1}^{n} \delta_{1k} (T_{1k} - \tau_1)^2 \sum_{k=1}^{n} \delta_{1k} (\beta_k - \bar{\beta})^2\right]^{1/2}}$$
(37)

where  $\beta_k$  (k = 1, . . ., n) is the zenith angle of the Sun at the time of the kth sounding (calculated from dates, times, longitudes, and latitudes) and  $\bar{\beta}$  is the average of the  $\beta_k$  values. There were no missing  $\beta$  observations since sufficient information was provided with the data to calculate  $\beta$  for each profile.

A linear regression of  $T_1$  on  $\beta$  is

$$T_1 = \tau_1 + \frac{r_{T\beta}\sigma_1}{\sigma_{\beta}} (\beta - \bar{\beta}) + \sigma_1(1 - r_{T\beta}^2)^{1/2} x_1$$
 (38)

where  $\sigma_{\beta}$  is the standard deviation of the  $\beta_k$  values and  $x_1$  is an independent standardized normal random number. This equation can be written as

$$t_1 = \alpha_0 + \alpha_1 \beta + \alpha_2 x_1 \tag{39}$$

where  $t_1$  is the standardized sea-level temperature defined by equation (6). The regression coefficients are, therefore, given by

$$\alpha_0 = -\frac{r_{T\beta}\bar{\beta}}{\sigma_{\beta}} \tag{40}$$

$$\alpha_1 = \frac{r_{T\beta}}{\sigma_{\beta}}$$
 (41)

$$\alpha_2 = (1 - r_{T\beta}^2)^{1/2}$$
 (42)

If each sounding had a sea-level temperature and if  $\tau_1=\bar{T}_1$  and  $\sigma_1=s_1$ , this method of defining regression coefficients would be equivalent to the usual least-squares method of fitting a line through the points  $\{(t_{1k},\beta_k);k=1,\ldots,n\}$ , where  $t_{1k}$  is the measurement of  $t_1$  in the kth sounding. Note that the mean and standard deviation of  $t_1$ , as defined by equation (39), are still 0 and 1, respectively, when averaged over the distributions of  $\beta$  and  $\tau_1$ , if it is assumed that the mean and variance of  $\beta$  are  $\bar{\beta}$  and  $\sigma_{\beta}^2$ , respectively.

Γ

## Estimating a<sub>0</sub>, a<sub>1</sub>, and a<sub>2</sub>

The method of estimating the linear regression of  $P_1$  on  $T_1$  (eq. (17)) is similar to that of  $t_1$  on  $\beta$ , the only difference being that  $P_1$  is not standardized. The regression coefficients are

$$a_0 = \overline{P}_1 - \frac{r_{TP}\sigma_P}{\sigma_1} \tau_1 \tag{43}$$

$$a_1 = \frac{r_{TP}\sigma_P}{\sigma_1} \tag{44}$$

$$a_2 = \sigma_P(1 - r_{TP}^2)^{1/2}$$
 (45)

where  $\bar{P}_1$  and  $\sigma_P$  are the sample mean and standard deviation, respectively, of sea-level pressure, and  $r_{TP}$  is the coefficient of linear correlation between  $T_1$  and  $P_1$  defined by

$$r_{TP} = \frac{\sum_{k=1}^{n} \delta_{1k} \delta_{1k} * (T_{1k} - \tau_{1}) (P_{1k} - \bar{P}_{1})}{\left[\sum_{k=1}^{n} \delta_{1k} \delta_{1k} * (T_{1k} - \tau_{1})^{2} \sum_{k=1}^{n} \delta_{1k} \delta_{1k} * (P_{1k} - \bar{P}_{1})^{2}\right]^{1/2}}$$
(46)

Notation for the pressure data corresponds to that for temperature data in that  $P_{1k}$  is the measurement of  $P_1$  in the kth sounding and  $\delta_{1k}$  is defined as

$$\delta_{1k}^{*} = \begin{cases} 1 & (\text{if } P_{1k} \text{ is present}) \\ 0 & (\text{if } P_{1k} \text{ is missing}) \end{cases}$$
(47)

## Estimating Parameters Without Data

In order to estimate a mean, a standard deviation, and a correlation coefficient, at least two data points are required. It is apparent from table II that this minimum requirement was not met at high altitudes in most categories. To complete the estimation of model parameters where data were totally missing, the following substitutions were used:

- (1) Means: Temperature means were estimated above available data by extrapolating the mean temperature profile by using the vertical temperature gradients from the 1966 U.S. Standard Atmosphere Supplements (ref. 2).
- (2) Standard deviations: Standard deviations of temperatures above available data were assumed to be equal to the nearest standard deviation that was based on data.
- (3) Coefficients of correlation: In situations where  $n_{ij} \le 3$ , the coefficient of correlation  $c_{ij}$  was estimated as

$$c_{ij} = \exp\left(-\frac{|i-j|}{2}\right) \tag{48}$$

This formula was chosen because it gave a fairly reasonable and simple representation of the observed correlation structure.

#### COMPARISON OF MODEL WITH DATA

In the present model evaluation, the model is compared with the same data set used in estimating the model parameters. Hence, the model's ability to imitate that data set is being demonstrated without any assurance that the data are adequate representations of the true population. As more and better data are acquired, they can be added to the present set and the model parameters updated. The model would then be expected to simulate the updated data sample with approximately the same accuracy as it does the present sample. Nevertheless, the model will, at best, only be as good as the data used to estimate its parameters.

To evaluate the model in terms of meeting its original objectives, samples consisting of 1000 model-generated atmospheres were created for each of the 17 latitude-season categories. In each model-generated sample, the means and standard deviations of  $T_i,\ P_i,\ D_i,\ \Delta T_i/\Delta z,\ \Delta P_i/\Delta z,\ and\ \Delta D_i/\Delta z$  were calculated and compared with corresponding properties in the data.

Figure 3 compares model and data means and standard deviations of T and  $\Delta T/\Delta z$  for the 15° latitude category. Solid lines represent model parameters based on the sample of 1000 modeled atmospheres, and the squares represent corresponding parameters for the data sample. Horizontal error bars are drawn to indicate 90-percent confidence intervals about the data estimates where these intervals extend beyond the data symbol. In places where horizontal error bars do not cross the model parameter curve, statistically significant differences between model and data exist. Note that such a significant difference exists between  $\sigma_i$  and  $s_i$  in the S(T) plot in figure 3 at altitudes of 96 and 99 km. These differences were deliberate, however, because of the choice of  $\sigma_i \neq s_i$ . It was believed that use of the higher  $s_i$  values would have significantly overestimated the frequency of large departures from the mean at these altitudes.

In the case of the mean and standard deviation of T, what is really being compared in figure 3 is the model's mean temperature  $\tau_i$  against the usual sample mean  $\overline{T}_i$ , given by equation (28), and the model's standard deviation  $\sigma_i$  against the sample standard deviation  $s_i$ , defined by equation (29). Had these model parameters been defined as  $\tau_i = \overline{T}_i$  and  $\sigma_i = s_i$ , there would have been no real differences found in the temperature comparisons in figure 3.

The amount of agreement between model and data samples of  $\Delta T/\Delta z$  is influenced largely by the agreement in model and data temperature samples. It can be shown that for the model samples, the mean and standard deviation of  $\Delta T_1/\Delta z$  are, respectively,

$$E\left(\frac{\Delta T_{i}}{\Delta z}\right) = \frac{\tau_{i} - \tau_{i-1}}{\Delta z} \tag{49}$$

$$S\left(\frac{\Delta T_{i}}{\Delta z}\right) = \frac{(\sigma_{i}^{2} + \sigma_{i-1}^{2} - 2\sigma_{i}\sigma_{i-1}c_{i-1,i})^{1/2}}{\Delta z}$$
(50)

Thus, any poor agreement between model and data temperature gradients could be a result of poor agreement between temperature means, standard deviations, and adjacent layer correlations. However, there may be other reasons for disagreement. Equations (49) and (50) do not have direct counterparts for the data samples, because the data sample of  $\Delta T_i/\Delta z$  consists of  $n_{i,i-1}$  observations whereas the samples of  $T_i$  and  $T_{i-1}$  contain, respectively,  $n_i$  and  $n_{i-1}$  observations.

The importance of this effect can be seen in figure 3 in the significant difference which exists between model and data samples of  $\Delta T/\Delta z$  at 66 km, despite good agreement between  $\tau$  and  $\overline{T}$  and between  $\sigma$  and s at 63 and 66 km. In this data set, the samples of  $T_{22}$  (at 63 km) and  $T_{23}$  (at 66 km) contained 486 and 136 values, respectively, and the sample of  $\Delta T_{23}/\Delta z$  contained 130 values. Thus, of the 486 profiles containing measurements of  $T_{22}$ , only 130 also contain measurements of  $T_{23}$ . The remaining 356 profiles end somewhere between 63 and 66 km. Apparently, the mean and standard deviation of  $T_{22}$  based solely on the 130 observations are significantly different from  $\overline{T}_{22}$  and  $s_{22}$  based on the entire sample of 486 values.

Figure 4 compares model and data means and standard deviations of P and  $\Delta P/\Delta z$  for the same latitude-season category. The values of E(P) and S(P) are nondimensionalized by the 1962 Standard Atmosphere pressures, and similarly, for purposes of nondimensionalizing, pressure gradients are expressed as percentage changes in pressure per kilometer,  $|\Delta P_i/\Delta z|/P_i$ . Because of the fact that pressures vary by several orders of magnitude between sea level and 99 km, dimensionalized plots of pressures and pressure gradients (on semilog paper) tend to mask or minimize differences between model and data parameters which are of the same order of magnitude.

Figure 5 compares model and data means and standard deviations of D and  $\Delta D/\Delta z$  for the 15° latitude category. As in the case of pressures, densities are nondimensionalized by using the 1962 Standard Atmosphere densities and vertical gradients are expressed as percentage changes in density per kilometer,  $|\Delta D_{\rm i}/\Delta z|/D_{\rm i}$ .

Means and standard deviations of  $P_i$ ,  $D_i$ ,  $\Delta P_i/\Delta z$ , and  $\Delta D_i/\Delta z$  are not directly controlled by the choice of model parameters (except for sea-level pressure), but result, instead, from the behavior of the hydrostatic equation and the equation of state when applied to model-generated random temperature profiles. There is no inherent guarantee with the empirical modeling procedure used that the distributions of pressures and densities in the model will match those in the data. In fact, since the solution of the hydrostatic equation involves an integration, systematic errors could be cumulative. Although a potential for significant disparity existed, the actual agreement seen in figures 4 and 5 is very satisfactory below 60 km.

Figures 6 to 53 represent the same comparisons as figures 3 to 5 for the remaining 16 latitude-season categories. The darkened symbols represent data samples consisting of only a single measurement, where standard deviations are zero and confidence intervals are undefined. These figures are included here not solely for model-data comparison purposes, but also because they contain valuable information about measured means and standard deviations of thermodynamic properties in the atmosphere.

In general, the agreement between model and data is satisfactory when the quality and quantity of the data base are considered. Below 60 km, agreement is excellent. Therefore, it is reasonable to conclude that below 60 km the model is limited only by the representativeness of the data in describing the true populations of interest. The sample sizes were, in general, adequate, but the time interval over which the data were collected (1969 to 1971) may have been too limited, and the sampling may not have been as random in latitude and time as one would desire. Thus, one may wish to add to the data base below 60 km if more representative data are acquired.

Above an altitude of 60 km, agreement between model and data deteriorates for a number of possible reasons. Obviously, the quantity of data at those heights is inadequate, but if sampling limitations are given, other significant differences exist between model and data. One possible reason for these differences is that the hydrostatic equation and the equation of state (with constant  $\overline{\mathbf{M}}$ ) are known to become less applicable. Also, the technique used to obtain the high-altitude data on the tape of 442 high-altitude soundings may have produced

biases or other faults in the data. Thus, pressure and density distributions derived by applying the hydrostatic equation and the equation of state to lower altitude distributions might actually be more realistic than those for the high-altitude data. Whatever the reason, the fact remains that the model's accuracy in representing atmospheric profiles above 60 km is uncertain.

The ultimate comparison between model and data is the comparison of histograms (frequency plots) of temperatures, pressures, and densities. As stated previously, no special effort was made to model the statistical distributions found in the data beyond an attempt to approximate their first two moments (means and variances). Temperature profiles were modeled as multivariate normal random vectors because of the desirability of the additive property of the normal distribution. Means and standard deviations of temperatures were selected which improved the normal fit somewhat, but no goodness-of-fit tests were made to determine the suitability of the normal distribution. Distributions of pressures and densities in the model (except for the sea-level pressure) were not normal. Figures 54 to 56 show comparisons of model and data temperature, pressure and density distributions at altitude intervals of 15 km between 0 and 90 km in the 150 latitude band. These comparisons are representative of similar comparisons at other altitudes and in other latitude-season categories.

## USING THE MODEL FOR MONTE CARLO SIMULATIONS

A computer program of the model entitled ERA, available through COSMIC (number LAR-12228) was developed for the Control Data CYBER system of computers at the NASA Langley Research Center. Random atmospheres generated by ERA are stored on an output file which can subsequently be linked to a Monte Carlo simulation program and a new independent atmosphere read at the beginning of each trajectory replication. For example, Monte Carlo simulations of space shuttle orbiter landings at the Kennedy Space Center during the summer might be of interest in the design of landing gear and runway length since low-density summer air means faster landings and longer braking distances. The ERA program can be called to provide any size sample of midday atmospheres from the 30° summer band. These atmospheres would be stored on a tape, and at the beginning of each landing replication the landing simulation program could read a new random atmosphere from the tape.

ERA generates atmospheres rapidly in spite of the model's use of large matrices. It takes less than 4 sec of central processor time on a CYBER 175 computer to generate 1000 random atmospheres from the same latitude-season category. This time includes the time required to determine the appropriate latitude-season category, read the parameters from the parameter tape, and then generate 1000 atmospheres from that category.

ERA is suitable for situations where one-dimensional atmospheres are needed. If two- or three-dimensional atmospheric variations are required, one should use a set of four computer tapes called REACT (COSMIC number LAR-12227) which contain three-dimensional global random atmospheres produced by the ERA model (ref. 18). The REACT tapes, one for each season, were generated by assuming a correlation structure relating adjacent atmospheric profiles over a global

grid. These tapes contain sufficient atmospheres to allow approximately 1400 independent replications of any three-dimensional spacecraft or aircraft trajectory.

#### CONCLUDING REMARKS

An empirical stochastic computer model, called ERA, has been developed for simulating random thermodynamic profiles in the Earth's atmosphere below an altitude of 100 km. Such profiles can be used in Monte Carlo studies of the effects of atmospheric variability on, for example, spacecraft or aircraft trajectories or on physical phenomena such as sound propagation or pollutant dispersions. Profiles of temperatures, densities, and pressures generated by the model are characteristic of any specified season, latitude zone, and time of day.

The objective of the ERA model is to provide large samples of random atmospheres which have the same statistical properties (for example, means, variances, and correlations) as a large data base containing data from over 6000 soundings. These data were used both to estimate model parameters and to evaluate the model's accuracy. In their former function, the data were divided into 17 latitude-season categories and a different set of parameters was estimated for each category. Model parameters, stored on a model parameter tape, include the mean and standard deviation of temperatures at altitude intervals of 3 km between sea level and 99 km and interlayer temperature correlations. Thus, statistical properties of modeled temperature profiles were controlled by the model input. Densities and pressures were computed by use of the equation of state and the hydrostatic equation.

The model gave an excellent representation of the data below an altitude of 60 km where data samples were of adequate size. Derived statistical properties at the discrete altitude levels which compared well with data were means and standard deviations of pressures and densities and vertical pressure and density gradients. Above an altitude of 60 km, the model's ability to simulate realistic atmospheric profiles is uncertain. Comparisons with data are inconclusive because of the diminished quantity, and possibly poor quality, of the data at those heights.

An efficient computer program of the ERA model, available through COSMIC (number LAR-12228), can generate 1000 random atmospheres from the same latitude-season category in less than 4 sec on a Control Data CYBER 175 computer. The program reads the appropriate model parameters from an auxiliary tape, which is a part of the program. The program and tape were generated under Control Data Network Operating System at the NASA Langley Research Center.

It is believed that the ERA model is the best available model for simulating realistic atmospheres because of the unified statistical approach used in modeling the data and because of the substantial quantity of data, particularly

below an altitude of 60 km, used in constructing the model. As new and better data become available, the model parameter tape can readily be updated and the model improved.

Langley Research Center National Aeronautics and Space Administration Hampton, VA 23665 June 28, 1977

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TABLE I.- NUMBER OF PROFILES IN THE DATA BASE FOR EACH LATITUDE-SEASON CATEGORY

Latitude		M-4-7			
band, deg	Spring	Summer	Winter	Total	
15		19	28	•	1928
30	495	468	516	504	1983
45	184	193	154	147	678
60	238	176	217	342	973
75	101	128	91	122	442
•				-	6004

TABLE II.- NUMBER OF TEMPERATURE OBSERVATIONS AT EACH ALTITUDE

IN THE 17 LATITUDE-SEASON CATEGORIES

			Numb	er (	of t					vati nds,		for	sea	sons	3	· <del>-</del>	
Altitude, km	Annual	Annual Spring					Summ	ıer	,		Autı	ımn		Winter			
	15	30	45	60	75	30	45	60	75	30	45	60	75	30	45	60	75
0 3 6 9	1747 1759 1771 1781	375 457 456 457	165 170 170 170	234 234 234 234	88 88 90	319 436 433 435	172 174 175 173	173 173 173 173	107 107 108	319 454 451 452	141 141 142	214 214 214 214	74 76 77	363 475 476 477	122 122 122	338 338 337 337	90 91 96 10
12 15	1778 1782	457 456	170 170	233 231		435 436	176 176	173 173	111 110	451 451	142 142	214 211		477 477	122 122	337 334	10 <sup>2</sup>
18 21 24 27 30 33	1781 1772 1774 1768 1749 1690	456 452 451 445 436 419	171 173 173 172 166 158	233 233 230 227 224 221	90 90 90 98	436 428 429 427 404 395	171 175 176 174 168 155		110 111 107 108 121 118	451 450 450 451 436 423	143 142 142 142 142 140	205	81 81 78 87	476 474 470 466 452 427	129 129 129 132 129 118	327 324 320 315 309 300	100 100 97 95 108
36 39 42 45 48 51	1616 1569 1556 1560 1530 1476	369 353 364 365 368 365	137 133 133 133 133 126	214 210 206 203 199 192	87 79 74 69	354 329 325 330 332 324	147 136 133 133 133 132	163 152 150 147 144 144	113 111 102 96 85 79	380 350 366 371 371 366	119 114 111 108 103 94	188 186 187 179	78 76 69	386 364 363 365 362 353		290 281 276 273 265 260	10 10 9 8 7 6
54 57 60 63 66 69	1369 1284 986 486 136 64	358 321 286 183 90 47	108 92 80 51 17 13	182 155 126 80 42 25	50 44 40 33	308 295 238 129 59 28	120 96 76 38 17 16	138 120 108 81 46 13	77 69 62 53 46 41	351 328 284 181 88 48	89 76 53 21 12 8	152 129 91 41		346 326 273 154 58 25	88 74 52 28 18 15	250 229 180 99 33 15	6 5 4 3 3
72 75 78 81 84 87	67 69 67 65 66 59	20 14 14 14 13 13	11 10 10 9 6 6	0	14	11 12 12 12 12 11 9	14 15 13 13 13 12	0 0 0 0 0	37 34 24 17 1	31 27 28 27 27 27 22	7 7 6 6 6 5	1 1 0 0 0	16	24 24 23 23 20 13	15 13 11 6 6 4	3 0 0 0 0	2 2 1
90 93 96 99	56 40 26 25	11 1 1 0	2 0 0 0	0 0 0	0 0 0	10 0 0	10 5 3	0 0 0	0 0 0 0	21 5 3 2	5 3 3	0 0 0	0 0 0	11 2 1 2	1 0 0 0	0 0 0 0	

TABLE III.- NUMBER OF PRESSURE OBSERVATIONS AT EACH ALTITUDE

IN THE 17 LATITUDE-SEASON CATEGORIES

A744444			Num	ber	of	tempo and		ure ( itude				for	sea	ason	3		
Altitude, km	Annual		Spr	ing			Sum	mer	Ī	Aut	umn			Winter			
	15	30	45	60	75	30	45	60	75	30	45	60	75	30	45	60	75
0 3 6 9 12 15	1790 1765 1776 1768 1785 1784	375 453 453 455 455 453			87 86 87 87 88 88	431 429 430 432	175 176	170 175 175 175 175 175	102 105 106 105 107 107	325 452 452 450 453 451	142 141 142 142	214 215 213 214 215 215	74 75 77 78	477 476 478 477	123 123 123 123	341 340 340	88 92 92 95 100 102
18 21 24 27 30 33	1777 1766 1741 1720 1694 1600	453 451 449 439 423 401	170 168 169 160	234 232 230 224 219 204	88 87 87 97	432 431 428 418 395 382	175 172 168	171 171 169 168 162 159	107 109 109 107 118 114		143 143 140 142	_	79 80 79 76 84 80	ı	130 129 127 129 127 115	326 316 307 290	102 99 93 91 102 94
36 39 42 45 48 51	1494 1432 1418 1416 1388 1337	336 317 326 329 331 331	135 132 133 132 131 123	186 171 170 165 158 152	91 80 72 67 62 56	300	142 134 132 131 131 129	150 132 128 126 124 121	110 105 96 89 78 71	357 316 332 340 338 337	119 113 109 106 101 93	167 155 150 148 141 139	76 71 70 64 57	343 340	103 99 99 98 96 93	244 233 225 222 215 211	89 82 73 62 52 49
54 57 60 63 66 69	1269 1155 883 432 123 60	327 301 263 169 85 49	110 95 82 52 17 12	145 124 96 60 37 22	50 43 37 36 31 28	275 259 205 111 52 27	119 97 77 38 17 16	113 100 87 70 40 12	68 64 59 52 46 40		87 74 51 20 11 8	129 120 102 73 35 11	47 45 42 34 26 23	323 305 258 140 55 24	86 72 52 28 18 15	203 185 144 84 30 15	44 42 36 30 29 29
72 75 78 81 84 87	64 66 62 60 61 55	22 15 13 13 12 13	11 10 10 10 7 6	8 1 0 0 0	23 22 19 14 0	13 11 11 11 11	16 15 14 14 13	1 0 0 0 0	37 34 24 17 1	31 27 27 26 27 22	7 7 6 6 6 5	2 1 1 1 0	21 21 18 16 4 2	22 24 24 22 19 13	15 13 12 8 6 5	3 0 0 0 0	28 26 21 17 2
90 93 96 99	54 40 27 25	10 1 1 0	4 0 0 0	0 0 0 0	0 0 0	10 1 1 2	9 5 3 3	0 0 0	0 0 0 0	22 5 3 2	5 3 3 4	0 0 0	0 0 0	11 2 1 3	2 1 1 1	0 0 0 0	0 0 0

TABLE IV.- NUMBER OF DENSITY OBSERVATIONS AT EACH ALTITUDE

IN THE 17 LATITUDE-SEASON CATEGORIES

_			Numb	er o	f t					rvati nds,		for	sea	sons			
Altitude, km	Annual		Summ	er		Autu	ımn	1	Winter								
	15	30	45	60	75	30	45	60	75	30	45	60	75	30	45	60	75
0 3 6 9 12 15	1744 1748 1753 1755 1734 1766	372 452 451 449 453 453	169	233	86	304 431 429 429 424 431	172 173 174 173 170 166	173 173 173 173	102 105 105 103 106 107	445	140 141	214	71	473 475	119 122 122 122 122 122	335 338 337 337 333 332	88 91 90 95 100 102
18 21 24 27 30 33	1762 1748 1727 1710 1680 1580	453 447 447 438 421 400	168 170 166 168 157 154	232 232 227 220 216 204	88	417 390	2 173 174 170 166 151	166 165	107 105 107 118	445 435 435 415	143 141 142 140 142 138	198 196	78 79 76 84	471 466 459 445	128	326 320 313 304 289 272	98 95 89 86 99 93
36 39 42 45 48 51	1487 1426 1411 1409 1377 1328	335 312 322 326 328 327	131 132	186 171 169 163 158 152	91 79 71 66 61 56	292 285 289 290	139 133 131 129 130 129	149 131 127 124 123 120	109 103 92 86 77 70	309 327 332 331	117 112 109 106 101 92	153 150 148 141	71 70 63 56	342 338 340 336	101 98 99 98 96 93	241 230 222 222 215 211	89 82 73 62 52 49
54 57 60 63 66 69	1257 1141 870 423 121 60	324 292 261 168 85 45	106 91 80 51 17 12	60 36	50 43 37 36 31 28		117 93 75 38 17 16	112 98 85 66 40	59 52 46	294 253 160 80	51 20 11	118 101 72 34	44 40 34	303 254 137 55	28	185 144 83 30	35 29 28
72 75 78 81 84 87	60 66 62 60 61 54	18 13 13 13 12 12	10 9 6	0 0 0	22 19 14 0	11 10 11 11	13	0	34 24 17	27 26 25 26	6 6 6	0 0	21 18 16	23 23 22 19	13 11 6 6	0 0	25 21 17 2
90 93 96 99	51 39 26 24	10 1 1 0	0	0	0	0	5	0 0		) 5	3	5 C		) 2			0

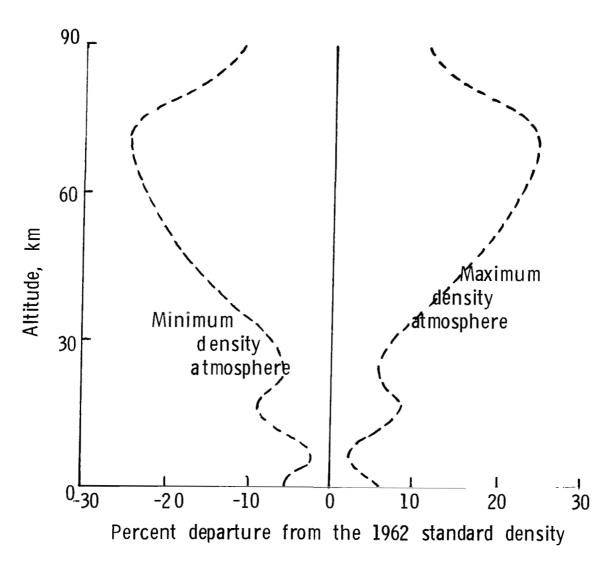


Figure 1.- "Extreme" atmospheres used in entry vehicle design studies.

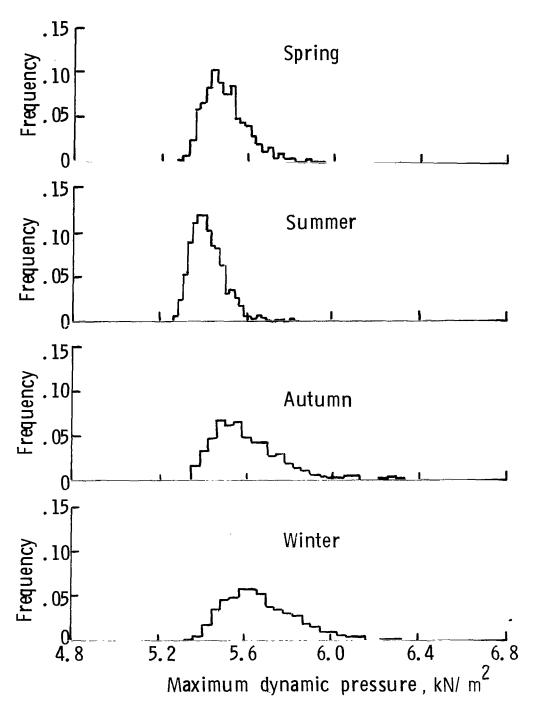


Figure 2.- Seasonal distributions of maximum dynamic pressure based on simulated shuttle entries.

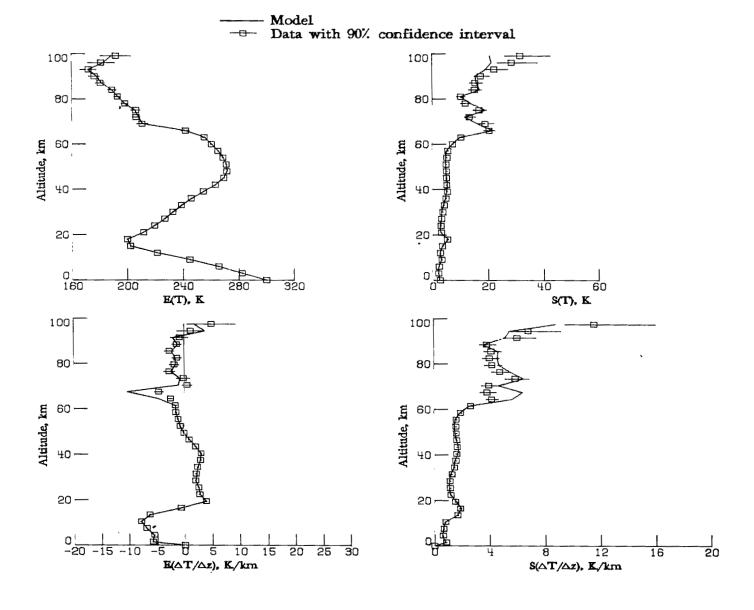


Figure 3.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the  $15^{O}$  latitude category.

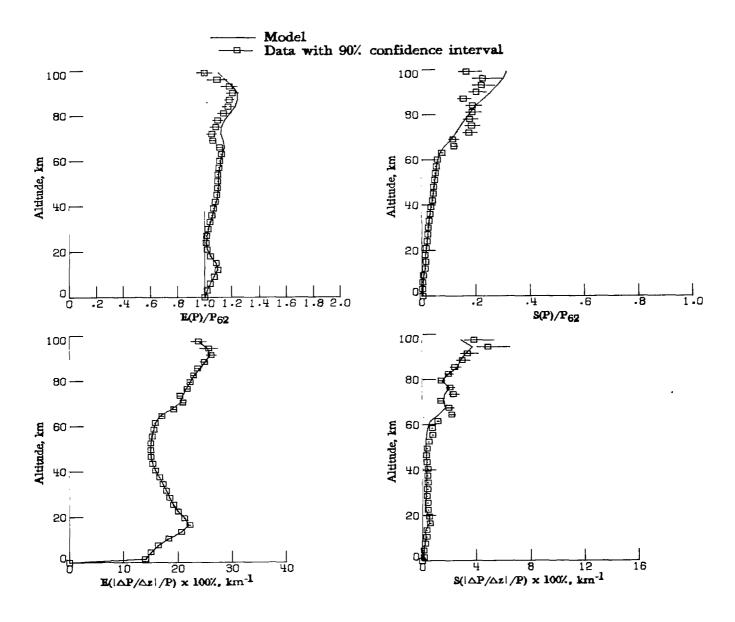


Figure 4.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the 15° latitude category.

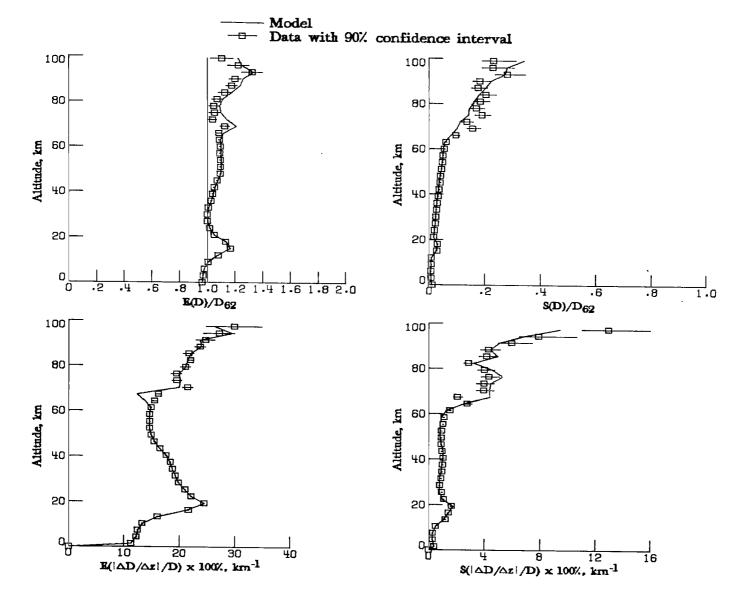


Figure 5.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the 15° latitude category.

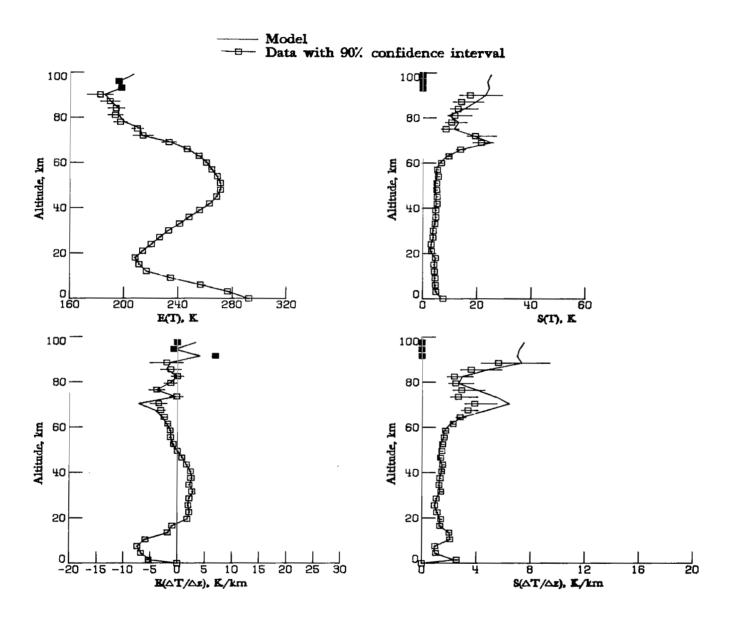


Figure 6.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the spring, 30° latitude category.

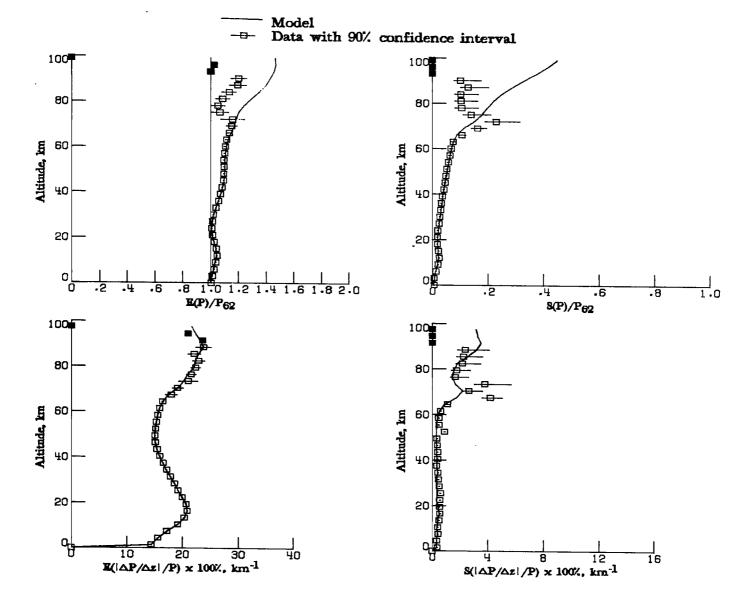


Figure 7.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the spring, 30° latitude category.

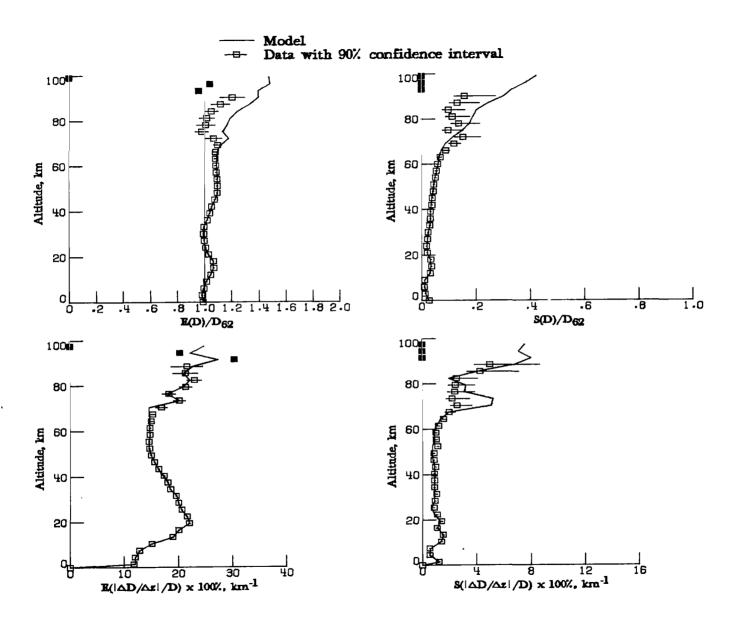


Figure 8.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the spring, 30° latitude category.

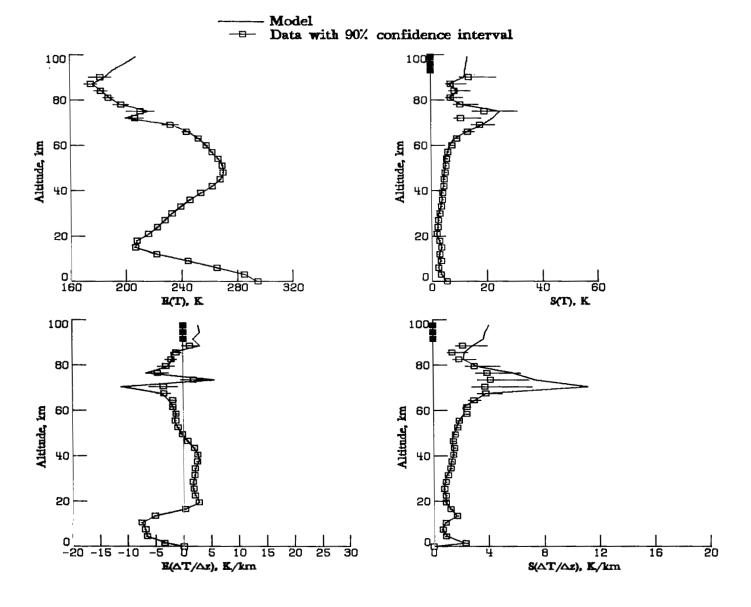


Figure 9.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the summer,  $30^{\circ}$  latitude category.

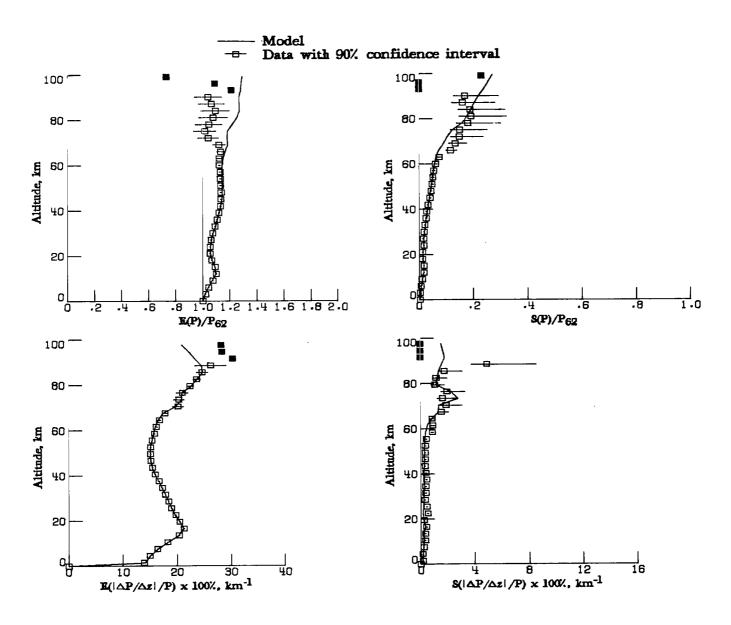


Figure 10.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the summer,  $30^{\circ}$  latitude category.

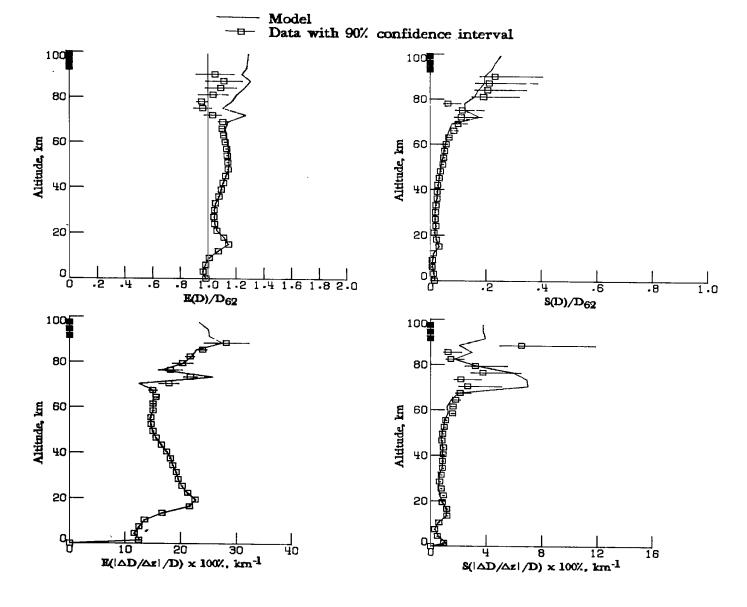


Figure 11.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the summer, 30° latitude category.

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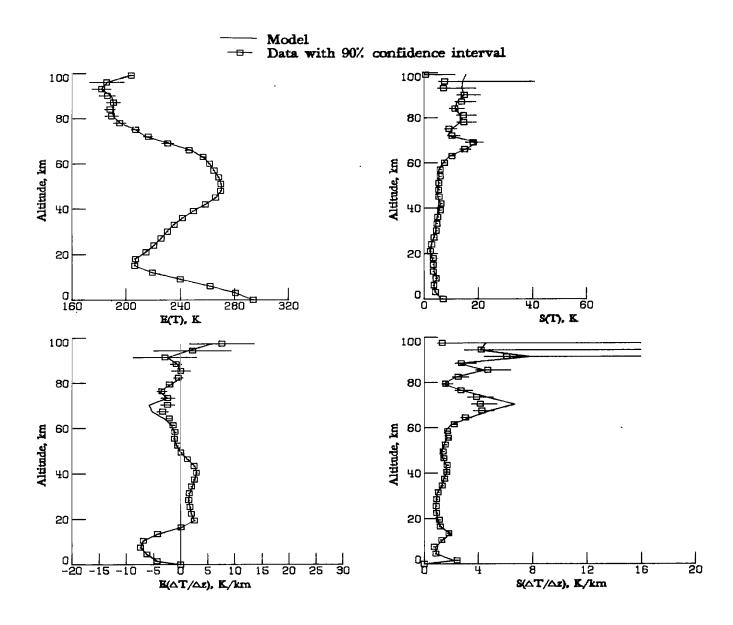


Figure 12.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the autumn, 30° latitude category.

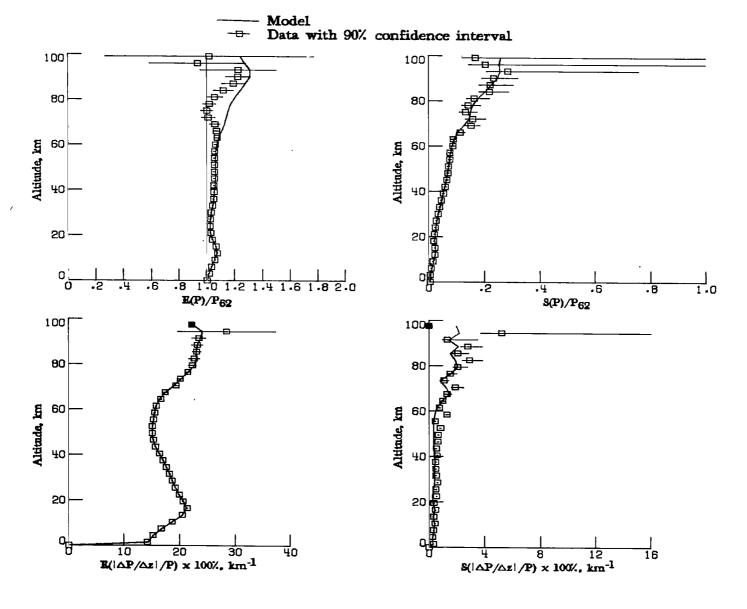


Figure 13.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the autumn, 30° latitude category.

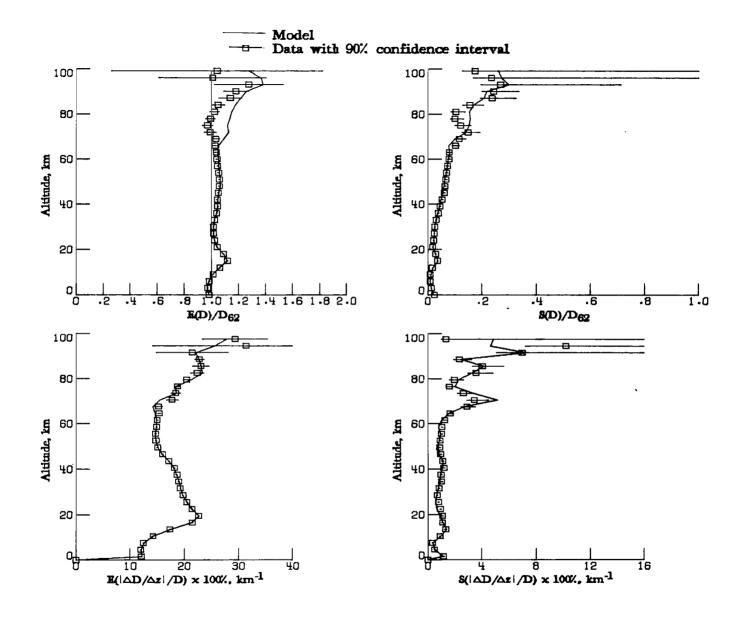


Figure 14.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the autumn,  $30^{\rm O}$  latitude category.

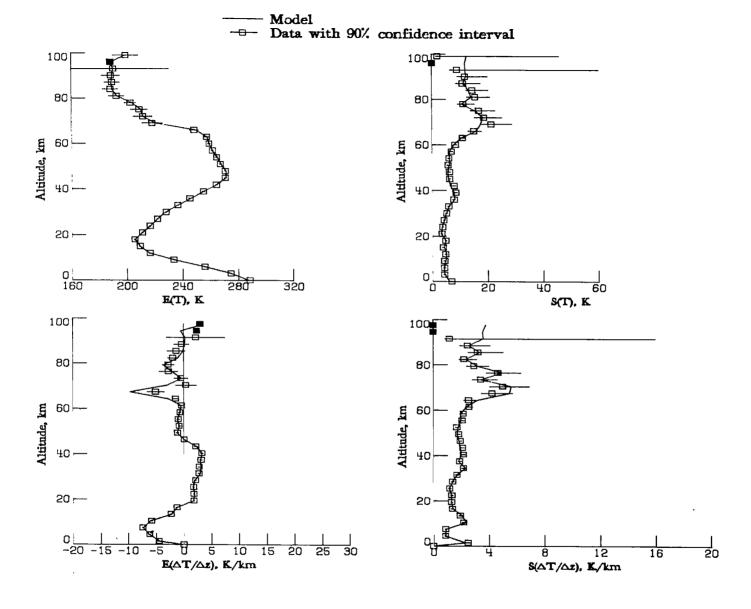


Figure 15.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the winter, 30° latitude category.

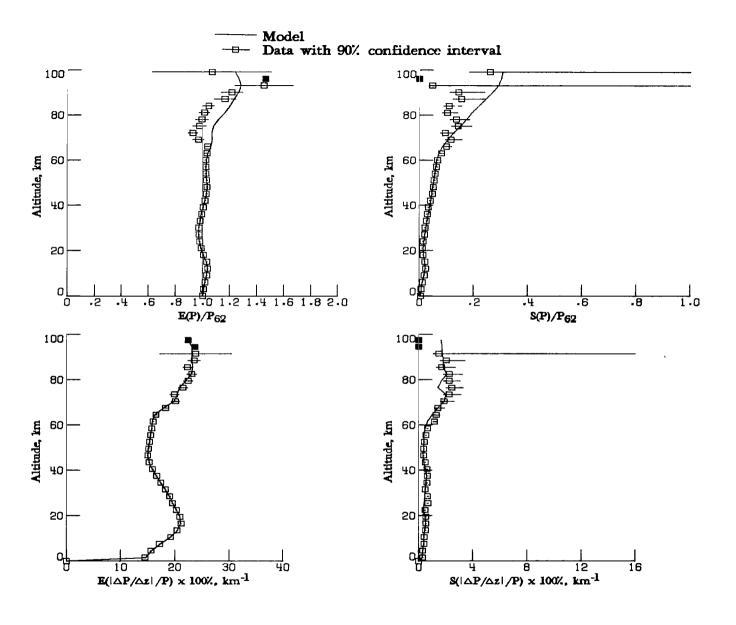


Figure 16.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the winter,  $30^{\circ}$  latitude category.

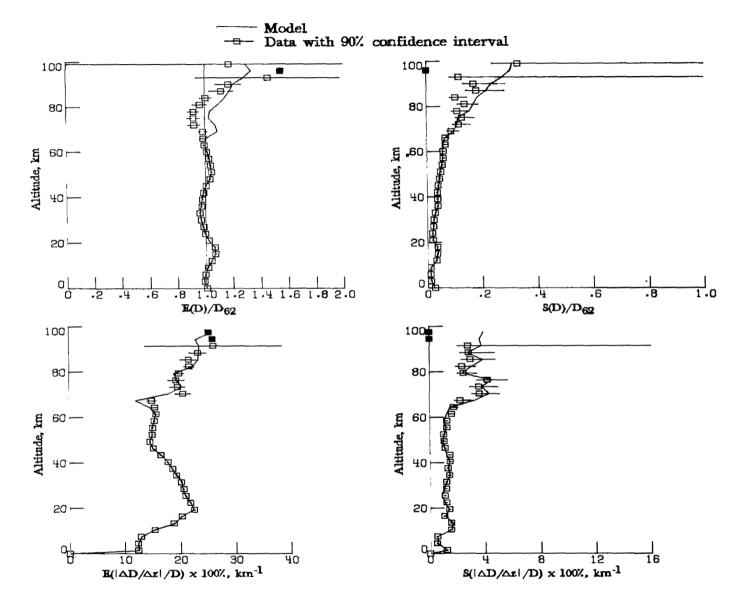


Figure 17.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the winter, 30° latitude category.

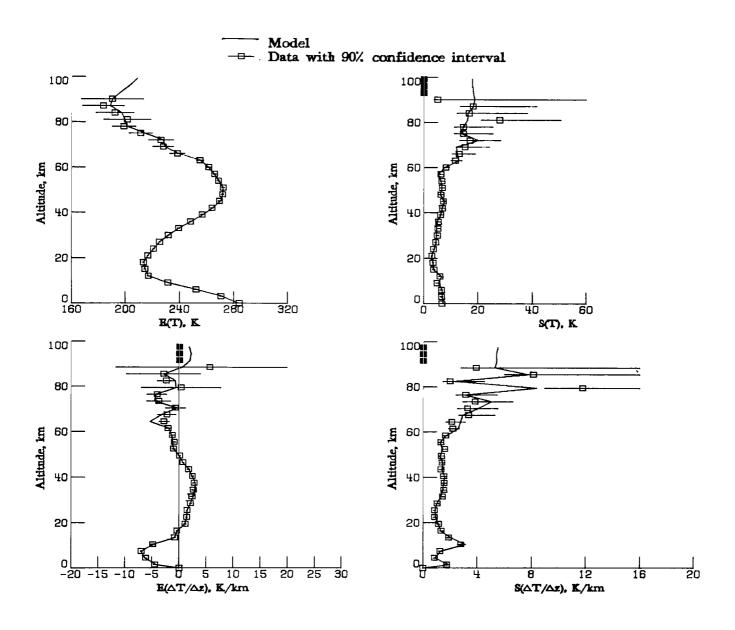


Figure 18.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the spring,  $45^{\rm O}$  latitude category.

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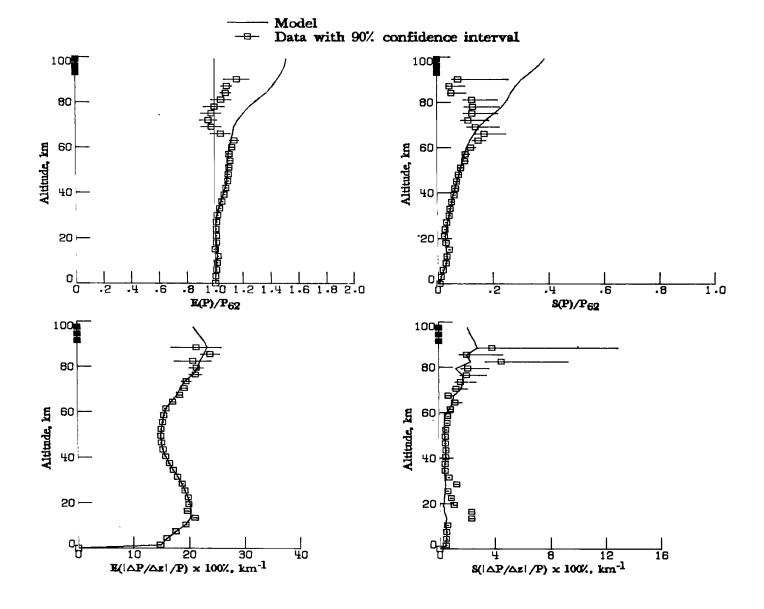


Figure 19.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the spring, 45° latitude category.

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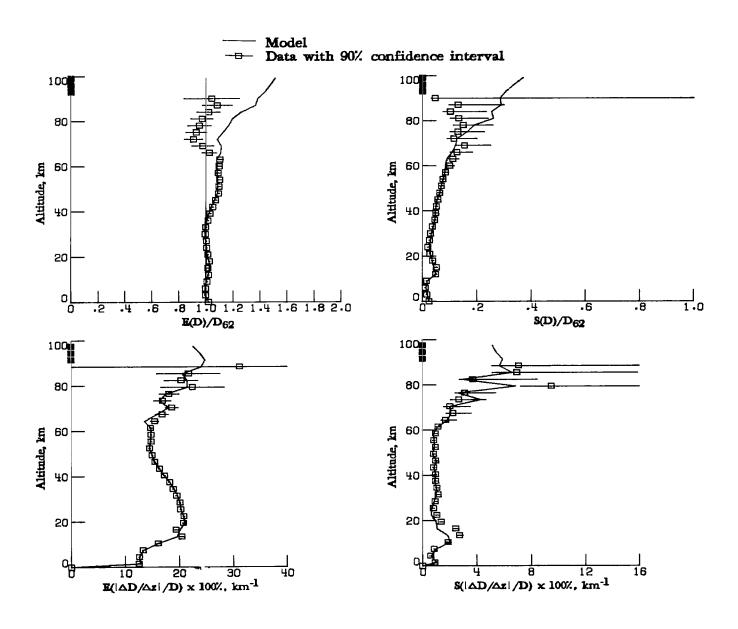


Figure 20.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the spring,  $45^{\circ}$  latitude category.

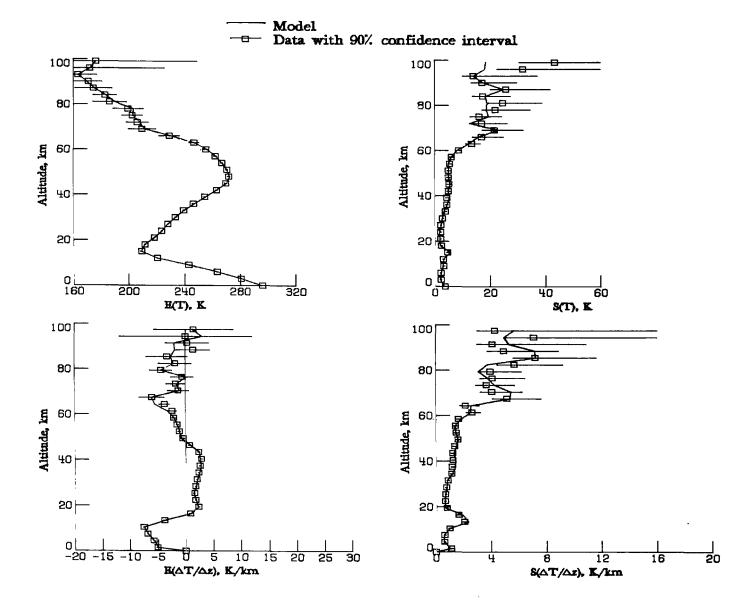


Figure 21.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the summer, 45° latitude category.

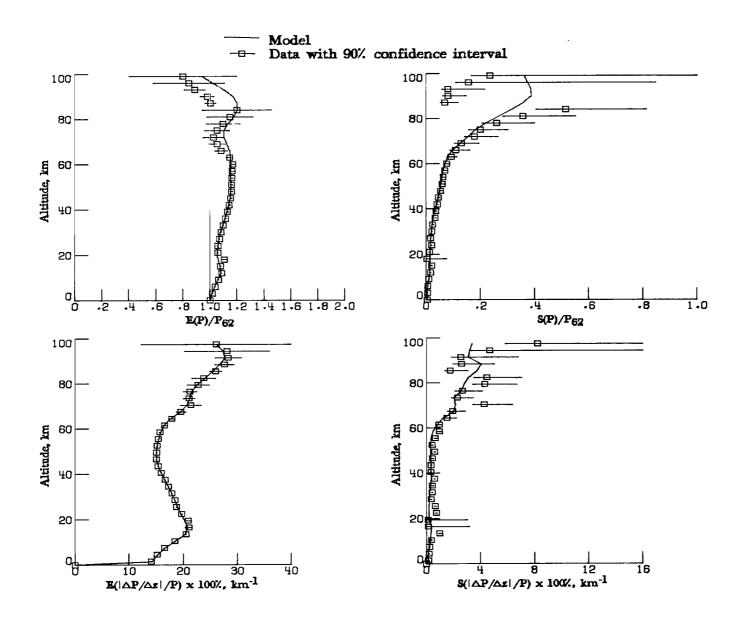


Figure 22.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the summer, 45° latitude category.

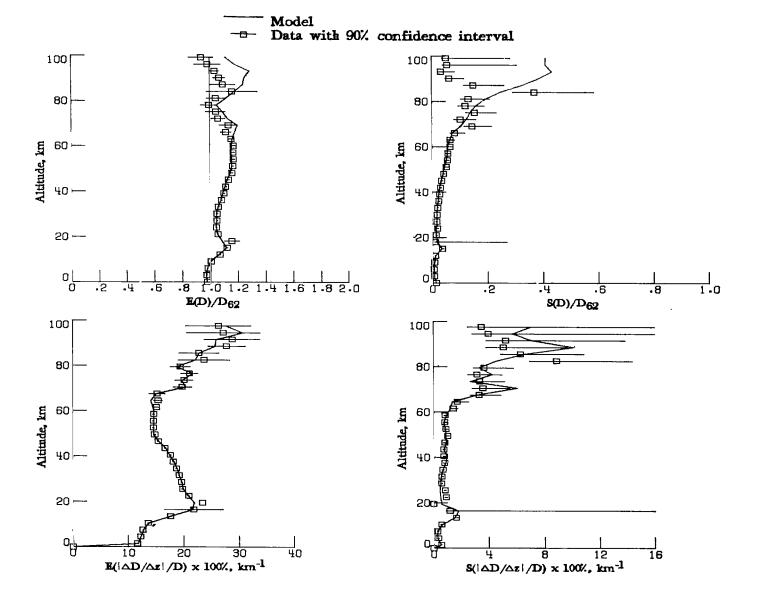


Figure 23.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the summer,  $45^{\rm O}$  latitude category.

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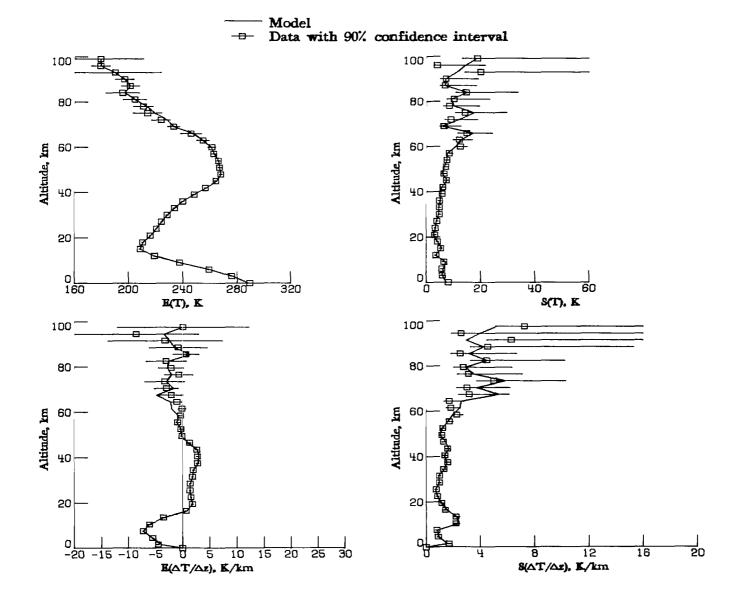


Figure 24.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the autumn,  $45^{\circ}$  latitude category.

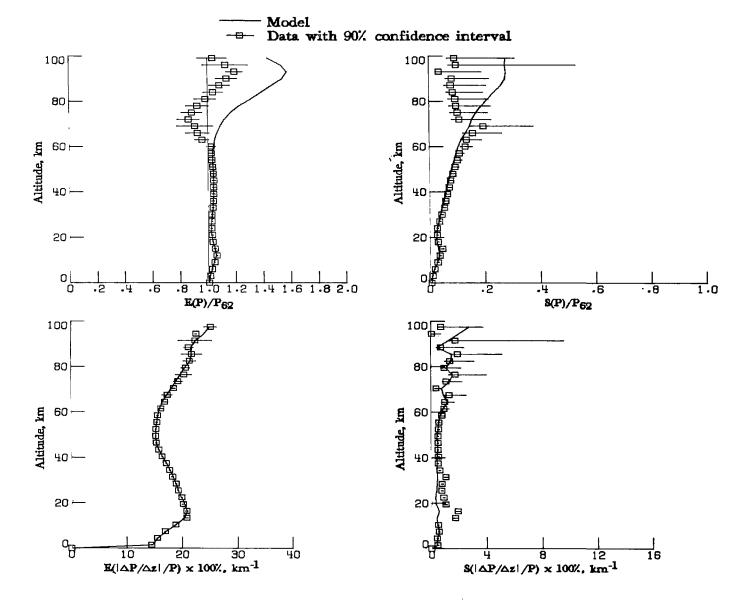


Figure 25.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the autumn,  $45^{O}$  latitude category.

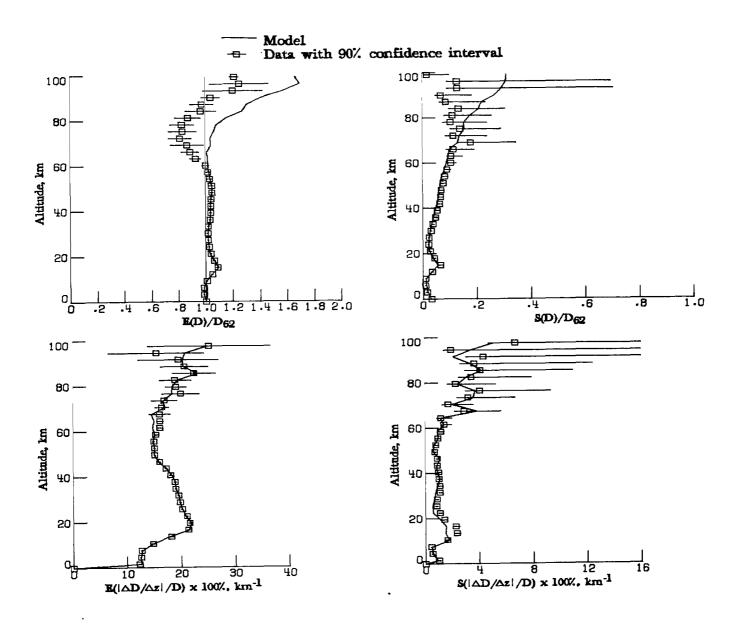


Figure 26.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the autumn, 45° latitude category.

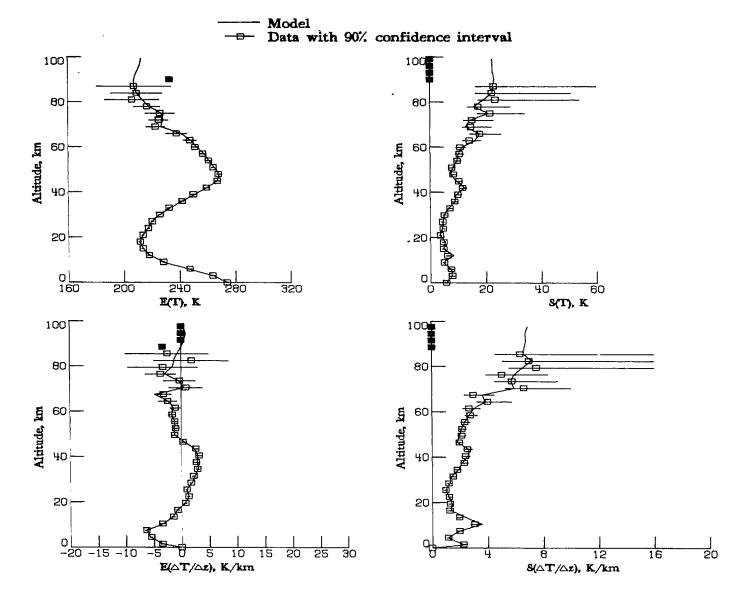


Figure 27.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the winter,  $45^{\rm o}$  latitude category.

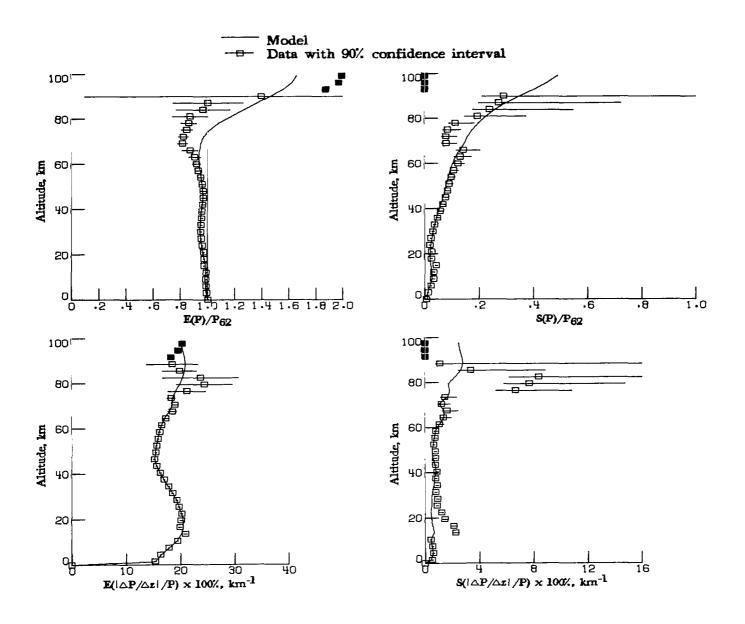


Figure 28.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the winter, 45° latitude category.

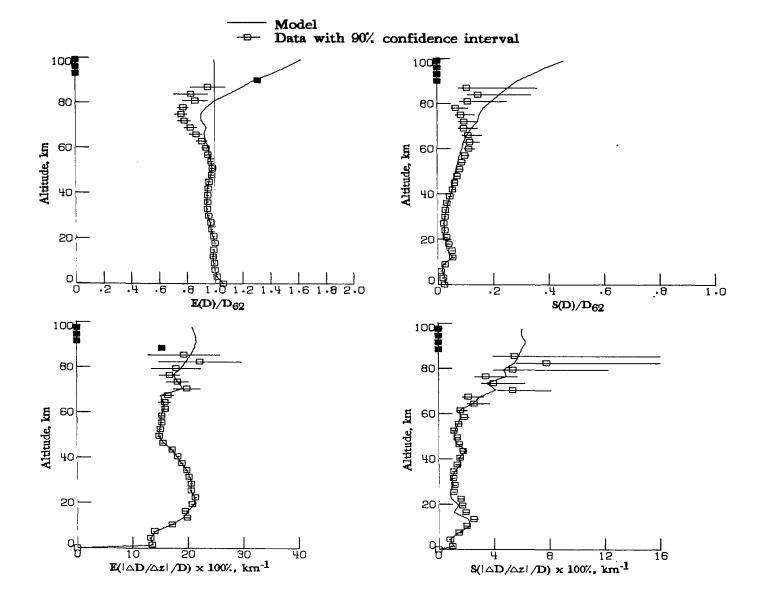


Figure 29.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the winter, 45° latitude category.

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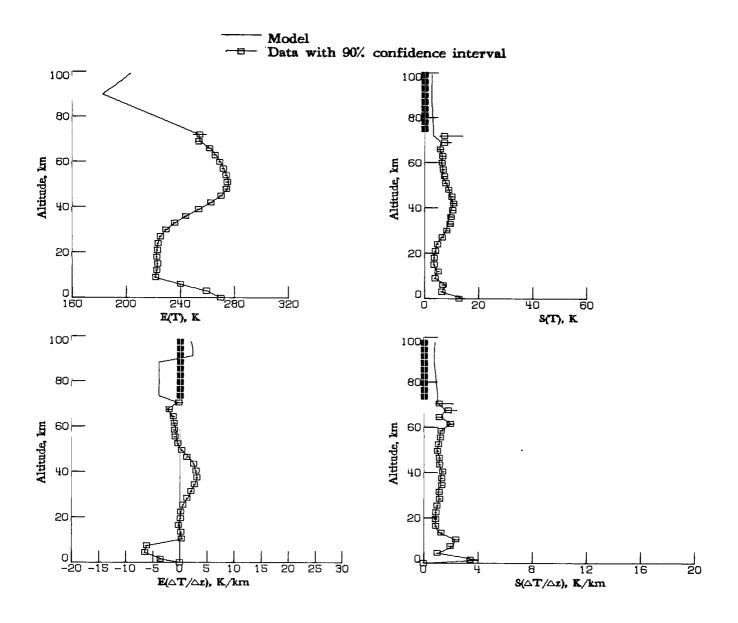


Figure 30.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the spring,  $60^{\circ}$  latitude category.

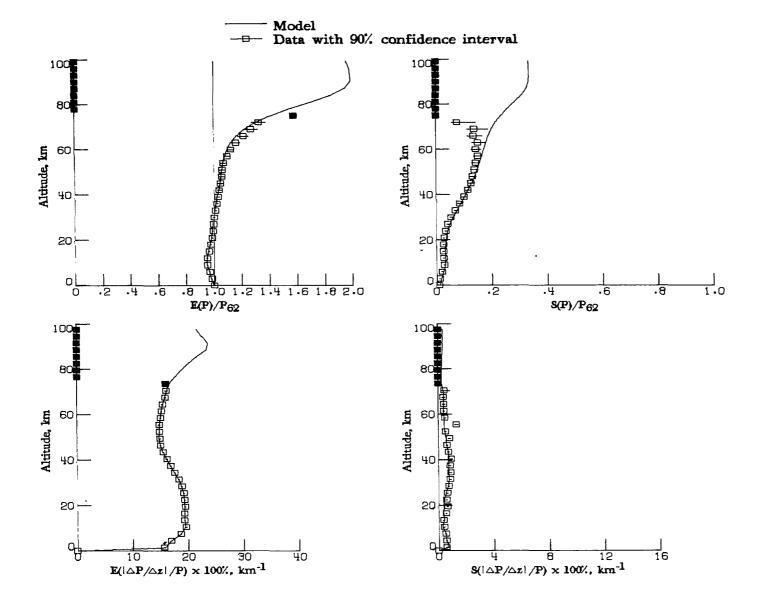


Figure 31.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the spring, 60° latitude category.

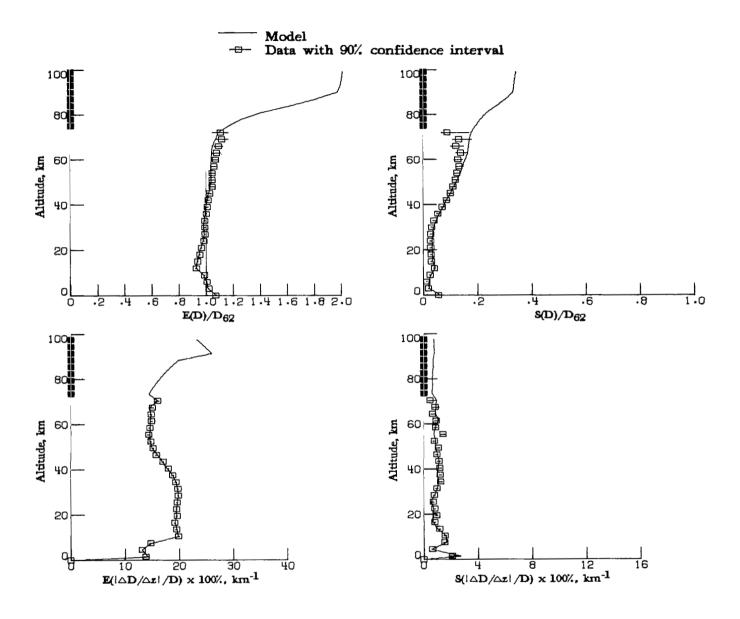


Figure 32.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the spring,  $60^{\circ}$  latitude category.

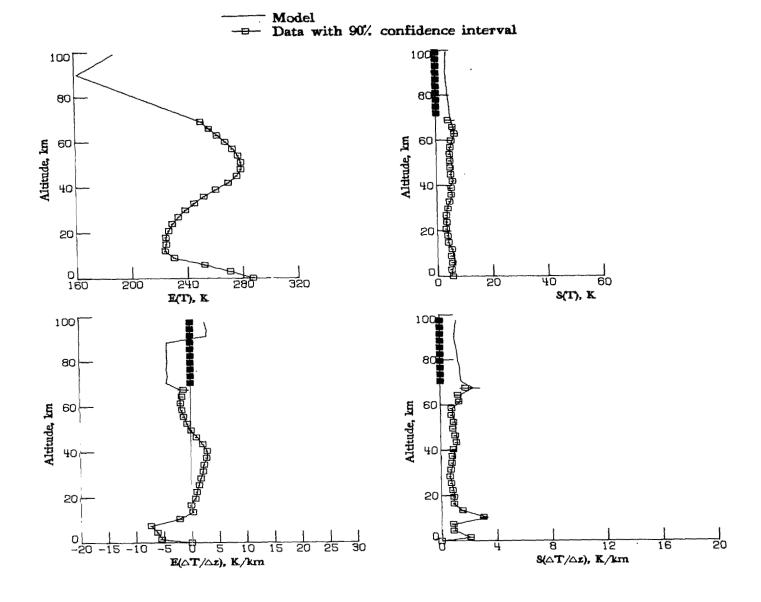


Figure 33.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the summer,  $60^{\circ}$  latitude category.

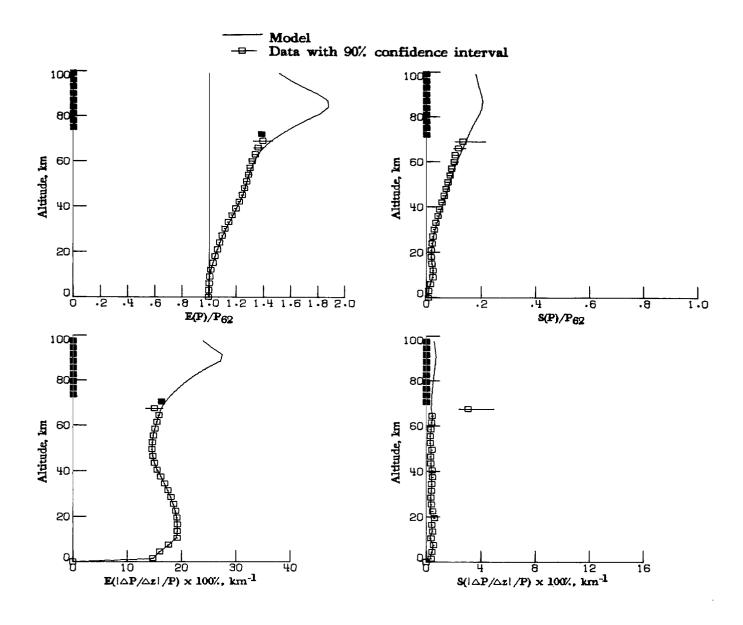


Figure 34.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the summer,  $60^{\rm O}$  latitude category.

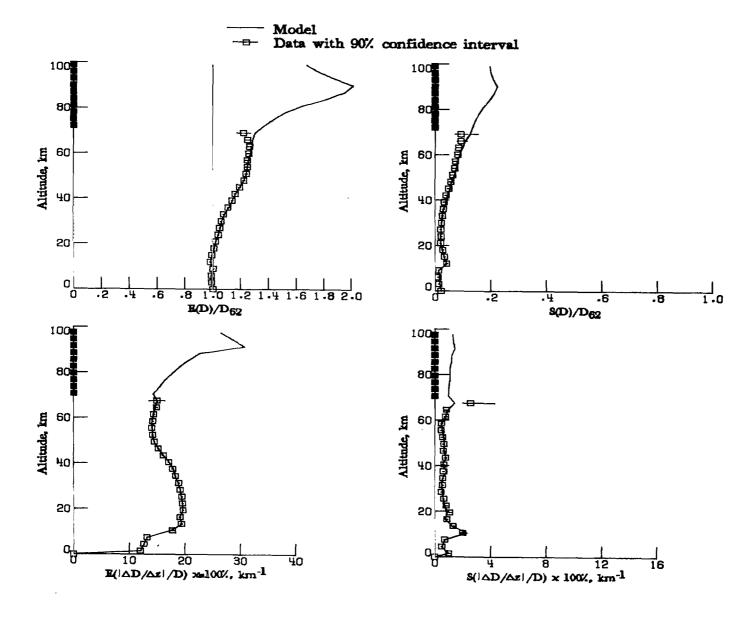


Figure 35.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the summer, 60° latitude category.

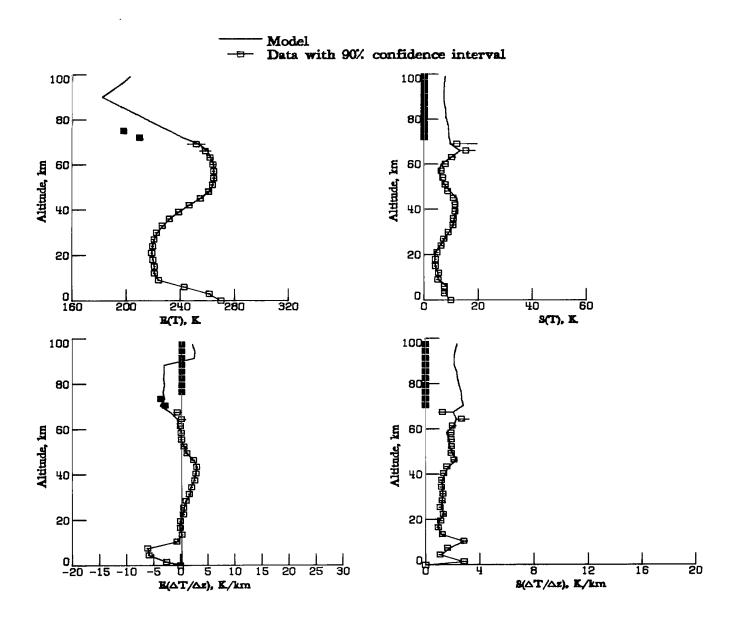


Figure 36.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the autumn,  $60^{\circ}$  latitude category.

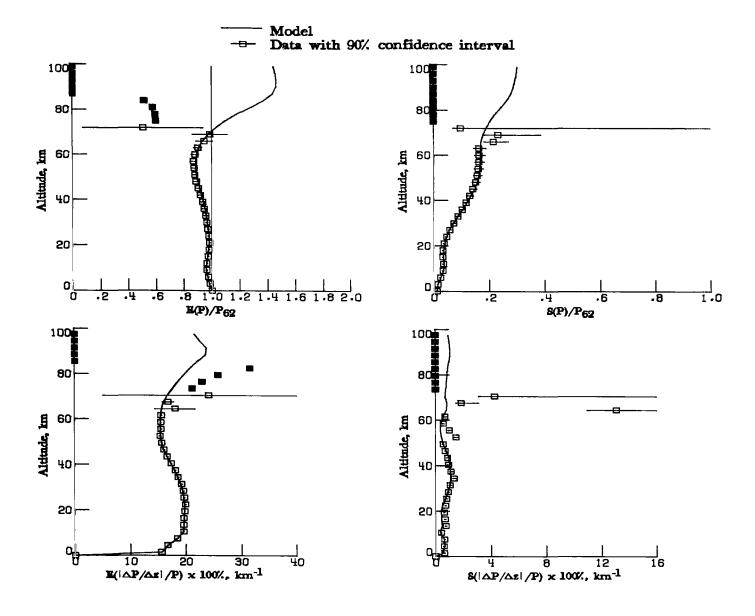


Figure 37.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the autumn, 60° latitude category.

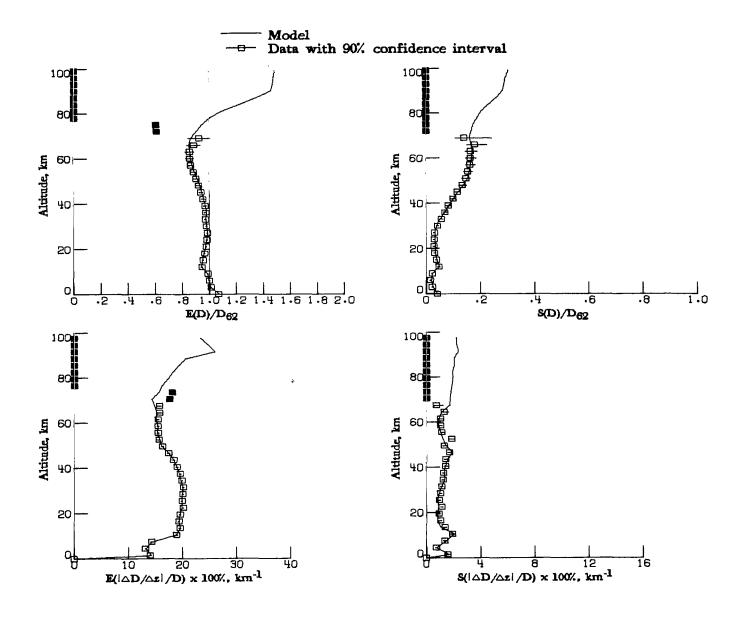


Figure 38.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the autumn,  $60^{\circ}$  latitude category.

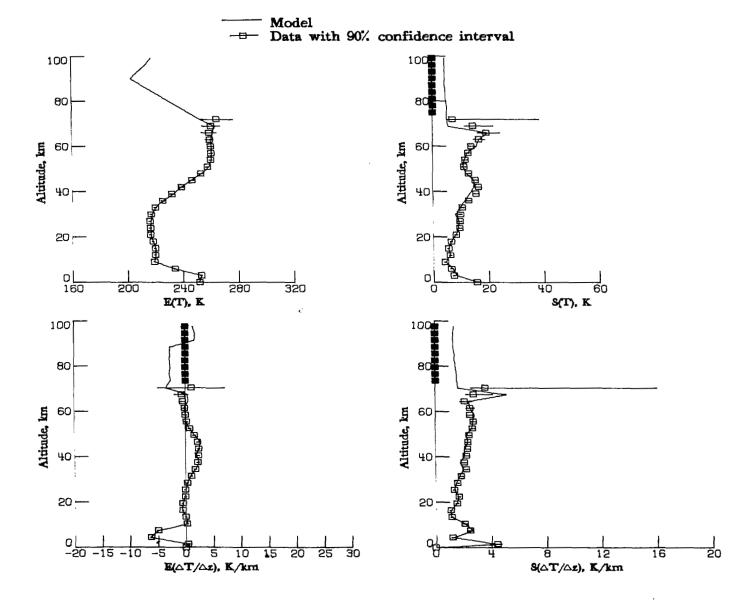


Figure 39.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the winter,  $60^{\rm O}$  latitude category.

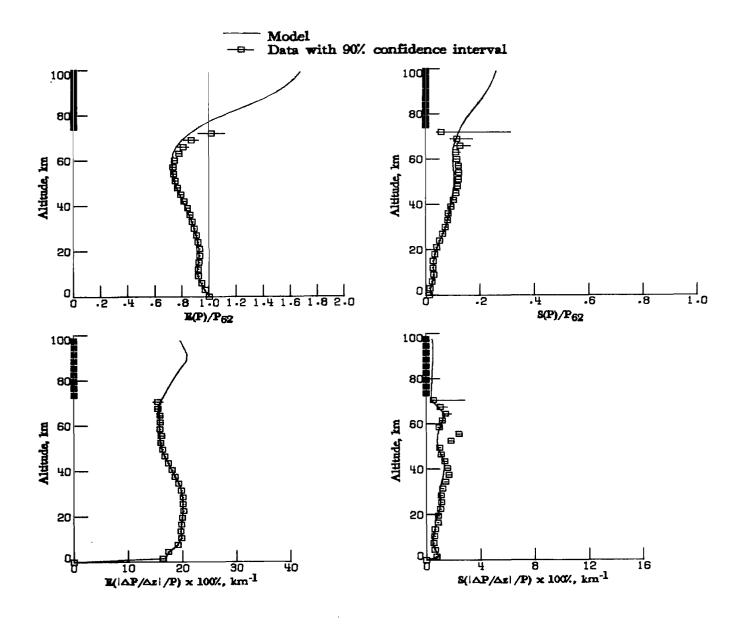


Figure 40.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the winter,  $60^{\circ}$  latitude category.

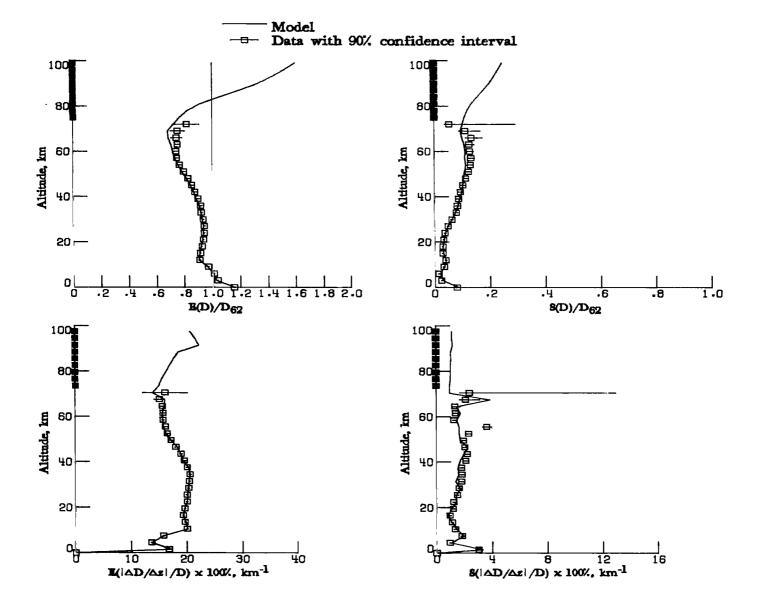


Figure 41.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the winter,  $60^{\rm O}$  latitude category.

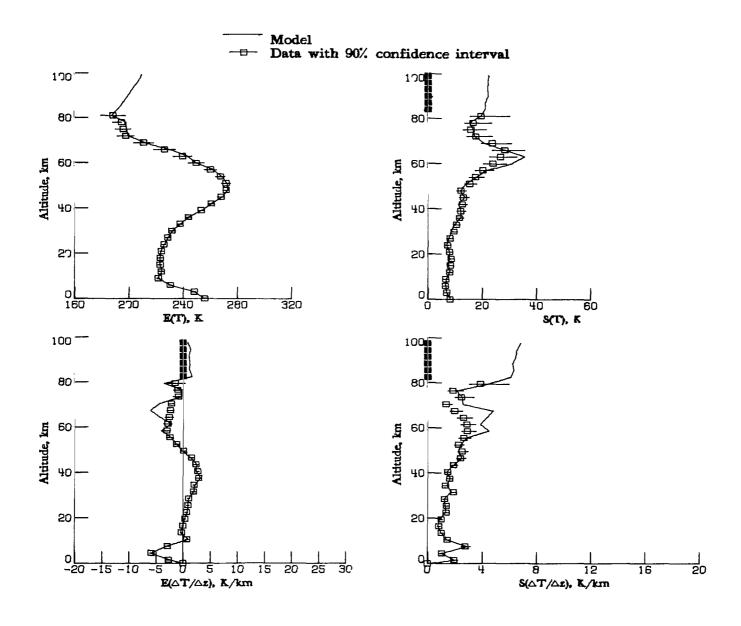


Figure 42.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the spring, 75° latitude category.

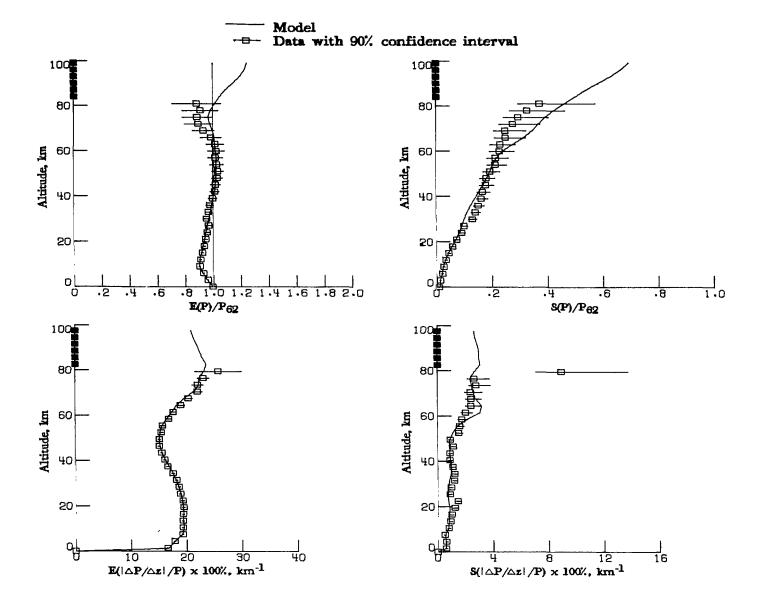


Figure 43.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the spring, 75° latitude category.

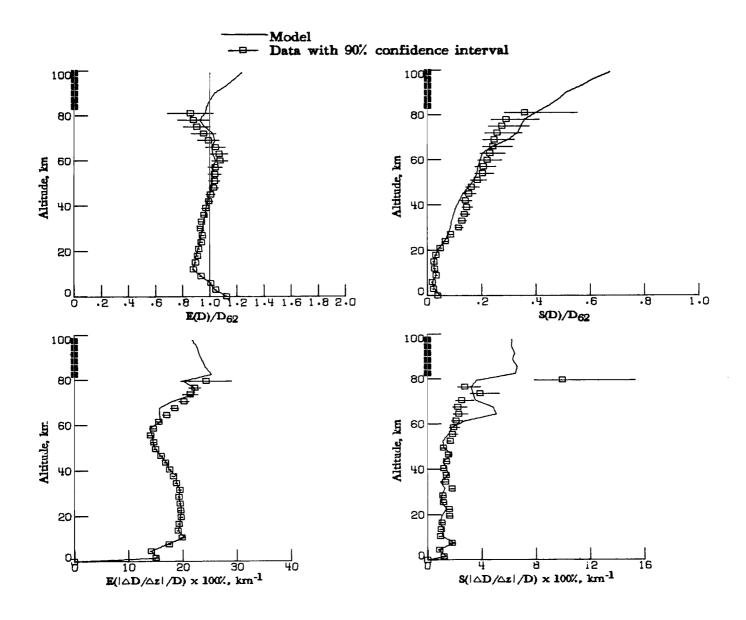


Figure 44.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the spring,  $75^{\circ}$  latitude category.

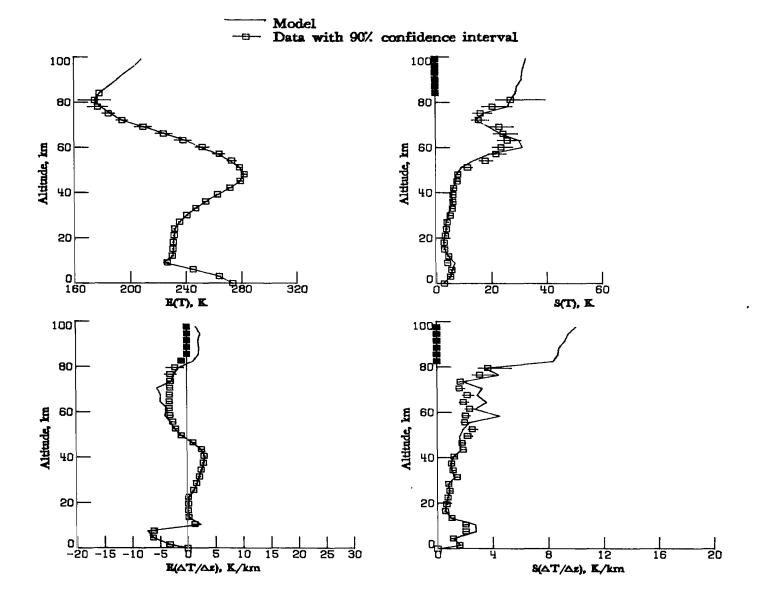


Figure 45.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the summer, 75° latitude category.

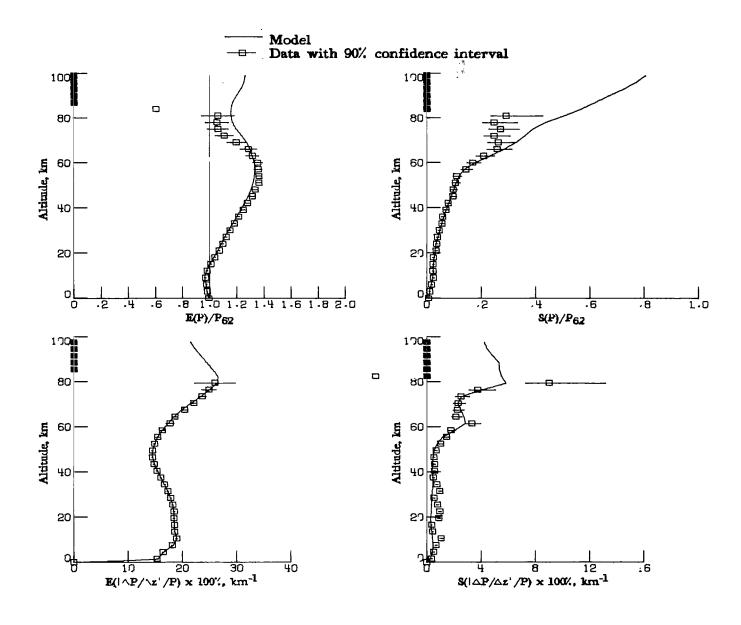


Figure 46.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the summer,  $75^{\circ}$  latitude category.

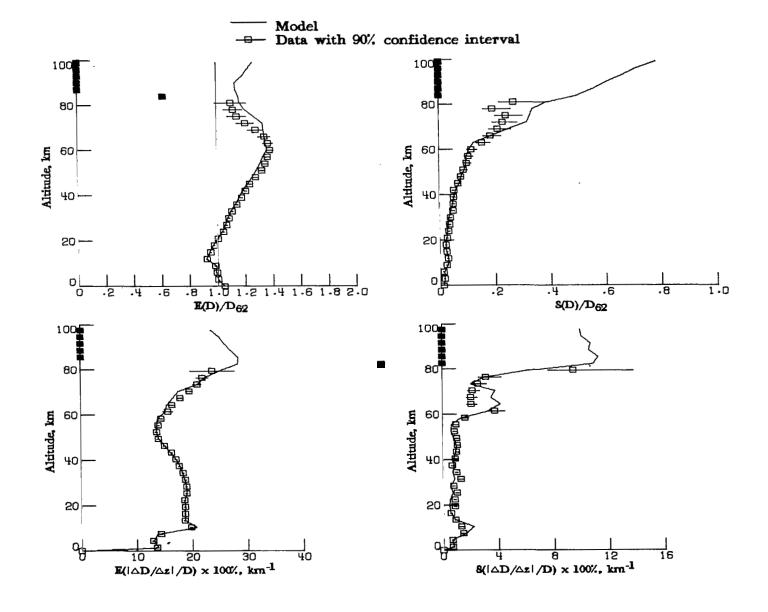


Figure 47.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the summer, 75° latitude category.

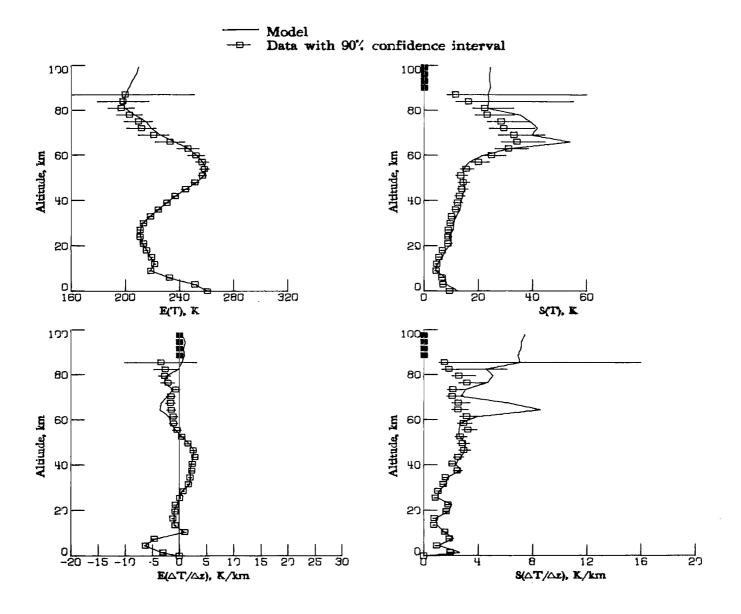


Figure 48.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the autumn, 75° latitude category.

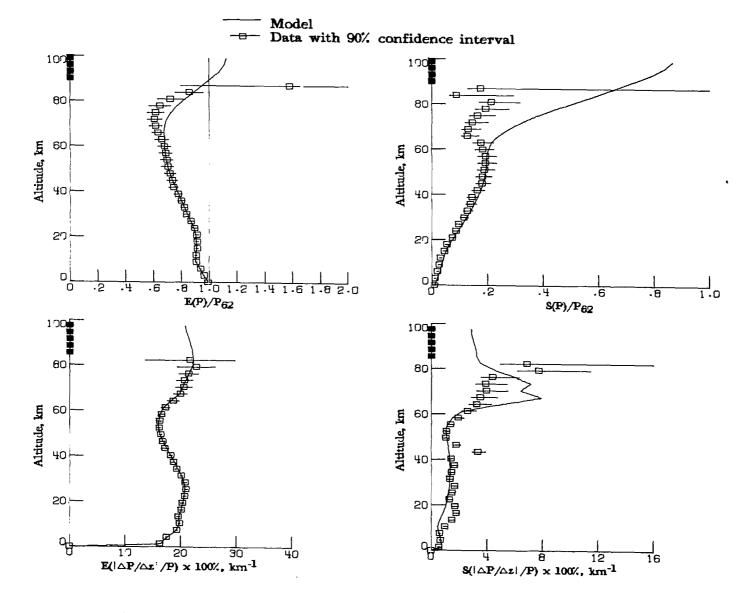


Figure 49.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the autumn,  $75^{\rm O}$  latitude category.

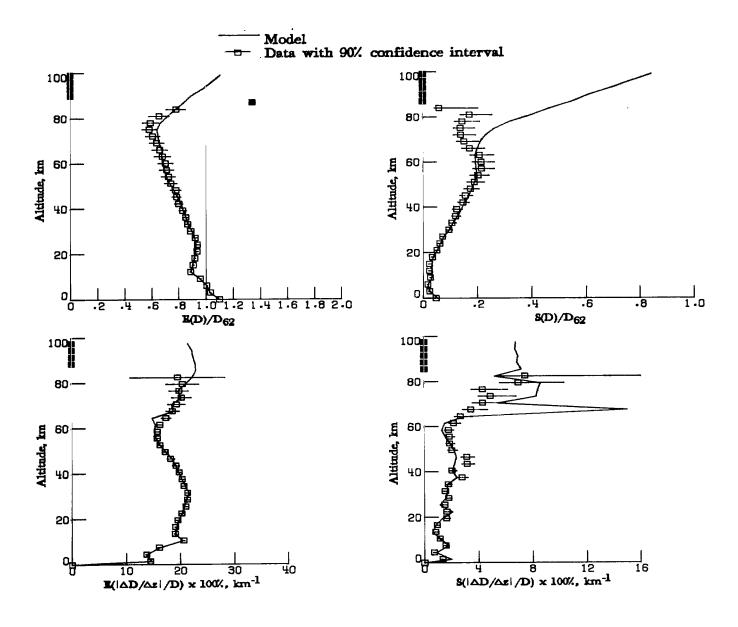


Figure 50.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the autumn, 75° latitude category.

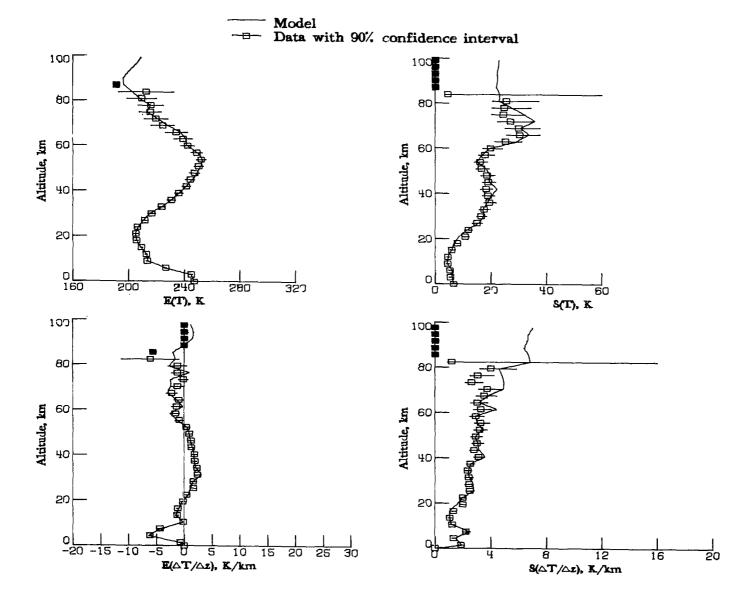


Figure 51.- Comparison of model and data means and standard deviations of T and  $\Delta T/\Delta z$  in the winter, 75° latitude category.

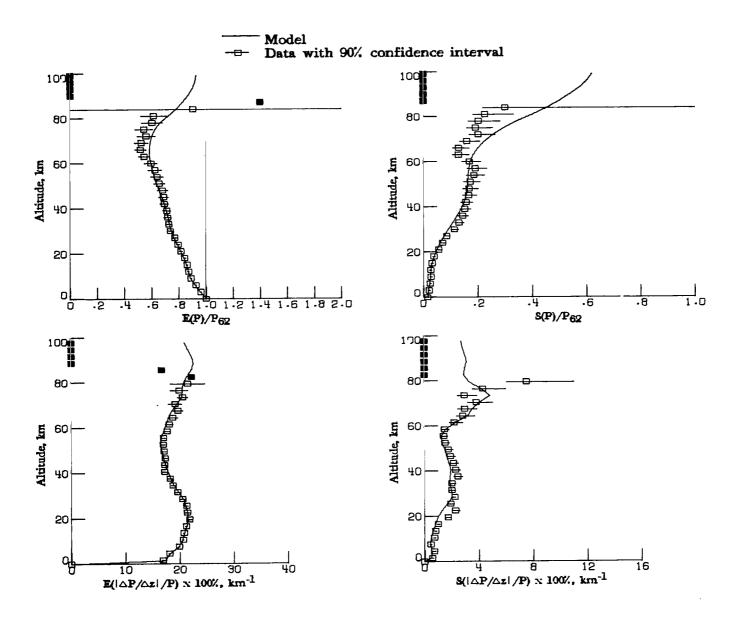


Figure 52.- Comparison of model and data means and standard deviations of P and  $\Delta P/\Delta z$  in the winter, 75° latitude category.

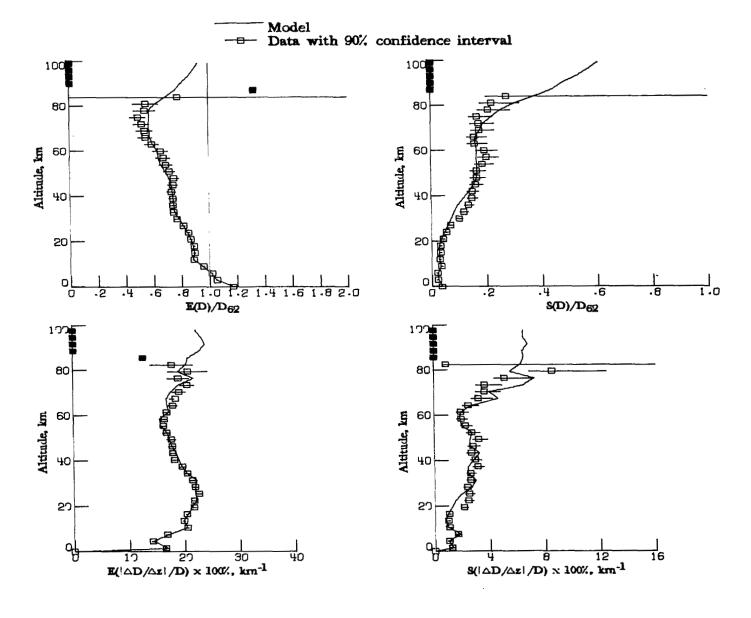


Figure 53.- Comparison of model and data means and standard deviations of D and  $\Delta D/\Delta z$  in the winter, 75° latitude category.

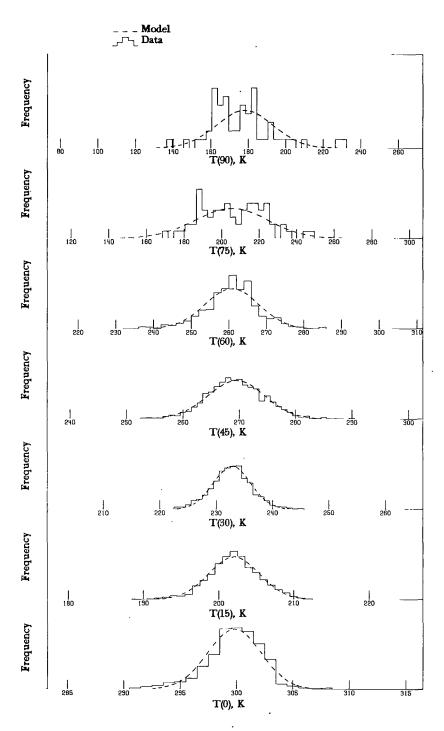


Figure 54.- Comparison of model and data temperature distributions at discrete altitude levels in the 15° latitude category.

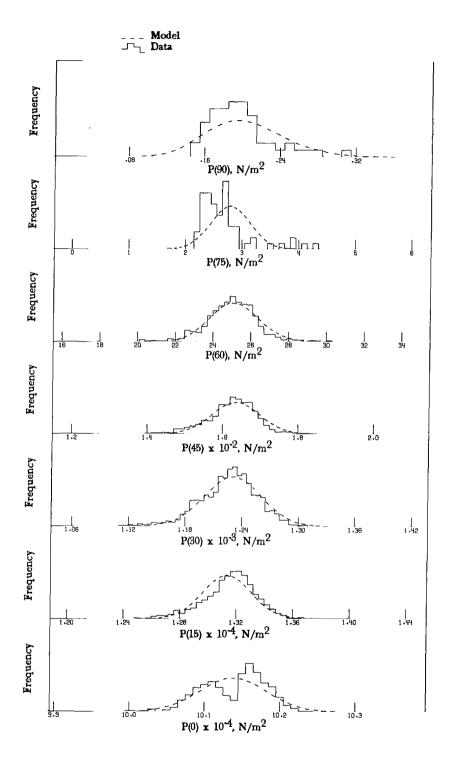


Figure 55.- Comparison of model and data pressure distributions at discrete altitude levels in the  $15^{\rm O}$  latitude category.

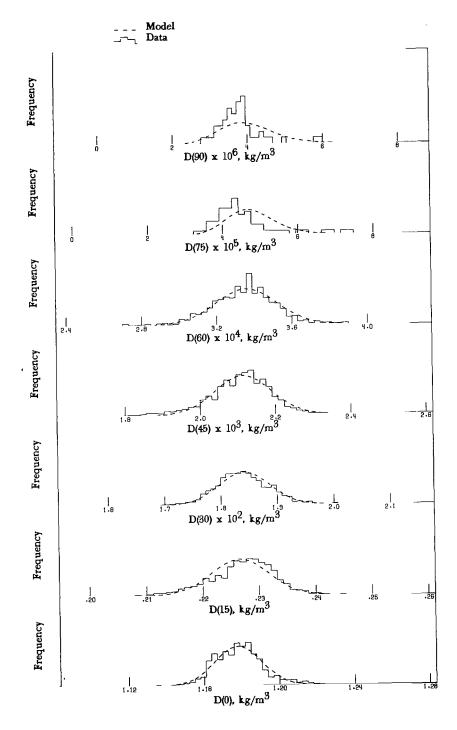


Figure 56.- Comparison of model and data density distributions at discrete altitude levels in the  $15^{\rm O}$  latitude category.

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